

Models UT350/UT320 Digital Indicating Controllers User's Manual

IM 05D01D02-41E

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IM 05D01D02-41E 4th Edition Blank Page

# Introduction

Thank you for purchasing the UT350/UT320 digital indicating controller.

#### Purpose Title Description Setup 1. Installation Describes the tasks (installation, wiring, and others) required to make the controller ready for operations. Describes examples of setting PV input types, control output Basic operation 2. Initial Settings types, and alarm types. Making settings described herein allows you to carry out basic control. Operating procedures 3. Operations Describes key operation sequences. and troubleshooting 4.1 Troubleshooting For operation control through external contact inputs, see "1.5 Terminal Wiring Diagrams." Brief operation 5. Parameters Contains the parameter map used as a guideline for setting and setpoint recording parameters and lists of parameters for recording User Settings.

### How to Use the Manuals

### Regarding This User's Manual

- (1) This manual should be provided to the end user. Keep an extra copy or copies of the manual in a safe place.
- (2) Read this manual carefully to gain a thorough understanding of how to operate this product before starting operation.
- (3) This manual describes the functions of this product. Yokogawa Electric Corporation (hereinafter simply referred to as Yokogawa) does not guarantee the application of these functions for any particular purpose.
- (4) Under absolutely no circumstances may the contents of this manual, in part or in whole, be transcribed or copied without permission.
- (5) The contents of this manual are subject to change without prior notice.
- (6) Every effort has been made to ensure that the details of this manual are accurate. However, should any errors be found or important information be omitted, please contact your nearest Yokogawa representative or our sales office.

### Safety Precautions

The following symbol is indicated on the controller to ensure safe use.



This symbol on the controller indicates that the operator must refer to an explanation in the user's manual in order to avoid the risk of injury or death of personnel or damage to the instrument. The manual describes how the operator should exercise special care to avoid electric shock or other dangers that may result in injury or loss of life.

The following symbols are used in the hardcopy user's manuals and in the user's manual supplied on the CD-ROM.

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Indicates that operating the hardware or software in a particular manner may damage it or result in a system failure.



Draws attention to information that is essential for understanding the operation and/or features of the controller.

### ■ Force Majeure

- (1) Yokogawa assumes no liability to any party for any loss or damage, direct or indirect, caused by the use or any unpredictable defect of the product.
- (2) No portion of the software supplied by Yokogawa may be transferred, exchanged, leased or sublet for use by any third party without the prior permission of Yokogawa.
- (3) Be sure to use the spare parts approved by Yokogawa when replacing parts or consumables.
- (4) Use this software with one specified computer only. You must purchase another copy of the software for use on each additional computer.
- (5) Copying this software for purposes other than backup is strictly prohibited.
- (6) Store the floppy disk(s) (original medium or media) containing this software in a secure place.

### Regarding Protection, Safety, and Prohibition Against Unauthorized Modification

- (1) In order to protect the product and the system controlled by it against damage and ensure its safe use, make certain that all of the instructions and precautions relating to safety contained in this document are strictly adhered to. Yokogawa does not guarantee safety if products are not handled according to these instructions.
- (2) Modification of the product is strictly prohibited.
- (3) Reverse engineering such as the disassembly or decompilation of software is strictly prohibited.



## Models UT350/UT320 Digital Indicating Controllers User's Manual

#### IM 05D01D02-41E 4th Edition

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# 1. Installation

This chapter describes installation, wiring, and other tasks required to make the controller ready for operation.

## 1.1 Model and Suffix Codes

Before using the controller, check that the model and suffix codes match your order.

| Model              | Suffix Code                                       |   | Description   |  |  |
|--------------------|---|---|---|--|--|
| UT350              |   |   | Digital indicating controller (provided with retransmission output and 15 V |  |  |
| UT320              | ]   |   | DC loop power supply as standard)   |  |  |
|                    | -0  |   | Standard type   |  |  |
| Туре               | -2  |   | Heating/cooling type  |  |  |
|                    | -3 Standard type (with 24 V DC loop power supply) |   | Standard type (with 24 V DC loop power supply)                              |  |  |
|                    |   | 0 | None  |  |  |
| Optional functions |   | 1 | With communication, heater burnout alarm                                    |  |  |
|                    |   | 2 | With heater burnout alarm   |  |  |

Check that the following items are provided:

- Digital indicating controller (of ordered model) ...... 1
- Brackets (mounting hardware) ..... 1 pair
- Unit label......
- User's Manuals ...... 3 (A2 size)
- User's Manual (Reference) (CD-ROM version) ...... 1

## 1.2 How to Install

To install the controller, select a location where:

- 1. no one may accidentally touch the terminals,
- 2. mechanical vibrations are minimal,
- 3. corrosive gas is minimal,
- 4. temperature can be maintained at about 23°C and the fluctuation is minimal,
- 5. no direct radiant heat is present,
- 6. no magnetic disturbances are caused,
- 7. no wind blows against the terminal board (reference junction compensation element),
- 8. no water is splashed,
- 9. no flammable materials are around,

Never place the controller directly on flammable items or equipment.

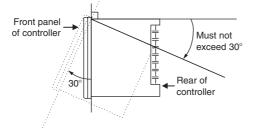
If the controller has to be installed close to flammable items or equipment, be sure to provide shielding panels all around the controller, at least 150 mm away from every side; the panels should be made of either 1.43 mm-thick metal-plated steel plates or 1.6 mm-thick uncoated steel plates.

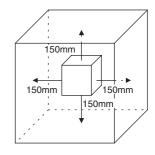
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Never touch the opening at the bottom of the case. It is to be used in the factory at shipping.

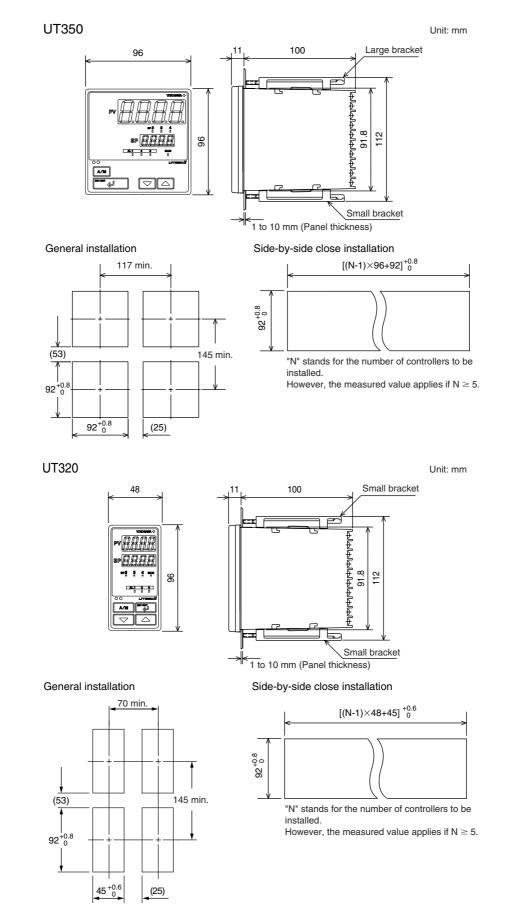
#### Installation Position

Install the controller at an angle within 30° from horizontal with the front panel facing upward. Do not install it facing downward. The position of right and left sides should be horizontal.





### External Dimensions and Panel Cutout Dimensions



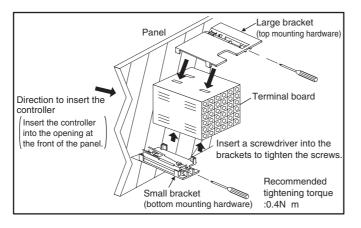
### How to Install



Turn off the power to the controller before installing it on the panel because there is a possibility of electric shock.

After opening the mounting hole on the panel, follow the procedures below to install the controller:

- 1. Insert the controller into the opening from the front of the panel so that the terminal board on the rear is at the far side.
- 2. Set the brackets in place on the top and bottom of the controller as shown in the figure below, then tighten the screws of the brackets. Take care not to overtighten them.

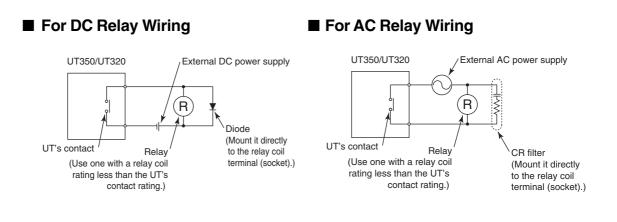


## **1.3 How to Connect Wires**

- 1) Before carrying out wiring, turn off the power to the controller and check that the cables to be connected are not alive with a tester or the like because there is a possibility of electric shock.
- 2) For the protection and safe use of the controller, be sure to place a circuit breaker (conforms with IEC60947, 5A, 100V or 220V AC) near the controller where the breaker can easily be operated. In addition, be sure to indicated that it is the instrument to cut the power supply of the controller.
- 3) Wiring must be carried out by personnel who have basic electrical knowledge and practical experience.

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- Provide power from a single-phase instrument power supply. If there is a lot of noise in the power line, insert an insulating transformer into the primary side of the line and use a line filter (recommended part: ZAC2205-00U from TDK) on the secondary side. As a countermeasures against noise, do not place the primary and secondary power cables close to each other.
- 2) For thermocouple input, use shielded compensating lead wires for wiring. For RTD input, use shielded wires that have low conductor resistance and cause no significant differences in resistance between the three wires. The cables to be used for wiring, terminal specifications, and recommended parts are as shown below.
- 3) Control output relays may be replaced. However, because they have a life of 100,000 times that of the resistance load, use auxiliary relays to turn on/off a load.
- 4) The use of inductance (L) loads such as auxiliary relays, motors and solenoid valves causes malfunction or relay failure; always insert a CR filter for use with alternating current or a diode for use with direct current, as a spark-removal surge suppression circuit, into the line in parallel with the load.
- 5) When there is possibility of being struck by external lightening surge, use the arrester to protect the instrument.

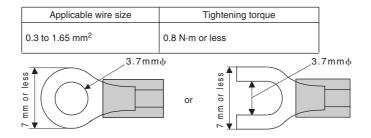


CAUTION

#### • Cable Specifications and Recommended Cables

| Purpose  | Name and Manufacturer   |
|--|---|
| Power supply, grounding, relay contact outputs | 600 V PVC insulated wires, JIS C 3307, 0.9 to 2.0 mm <sup>2</sup>                           |
| Thermocouple                                   | Shielded compensating lead wires, JIS C 1610, X-D-C-C (See Yokogawa Electric's GS 6B1U1-E.) |
| RTD  | Shielded wires (three conductors), UL2482 (Hitachi Cable)                                   |
| Other signals                                  | Shielded wires  |

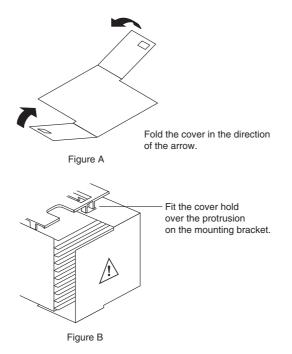
#### Recommended Terminal Lugs



#### • Terminal Covers (Optional parts)

| Target Model | Part Number | Sales Unit |
|--------------|-------------|------------|
| For UT350    | T9115YD     | 1          |
| For UT320    | T9115YE     | 1          |

- 1. Before attaching the terminal cover, bend the side with the groove inward as shown in Fig. A. Be careful not to bend it backwards. This not only marks it harder to attach the cover but will also weaken its hold.
- 2. Fit the holes on the top and bottom of the terminal cover the projections on the brackets (Fig. B) and lock in place. The figure right shows the attachment of a terminal cover to UT controller.



## 1.4 Hardware Specifications

#### **PV Input Signals**

- Number of inputs: 1 (terminals 11-12-13)
- Input type: Universal input system. The input type can be selected with the software.
- Sampling period: 250 ms
- Burnout detection: Functions at TC, RTD, standard signal (0.4 to 2 V or 1 to 5 V) Upscale, downscale, and off can be specified.
   For standard signal, burnout is determined to have occurred if it is 0.1 V or less.
- Input bias current: 0.05 μA (for TC or RTD b-terminal)
- Measurement current (RTD): About 0.13 mA
- Input resistance: 1  $M\Omega$  or more for thermocouple or mV input About 1  $M\Omega$  for DC voltage input
- Allowable signal source resistance: 250  $\Omega$  or less for thermocouple or mV input Effects of signal source resistance: 0.1  $\mu$ V/ $\Omega$  or less 2 k $\Omega$  or less for DC voltage input Effects of signal source resistance: About 0.01%/100  $\Omega$
- Allowable wiring resistance: for RTD input Maximum 150  $\Omega$ /wire: Conductor resistance between three wires should be equal However, 10  $\Omega$ /wire for a maximum range of -150.0 to 150.0°C. Wire resistance effect:  $\pm 0.1^{\circ}$ C/10  $\Omega$
- Allowable input voltage: ±10 V DC for thermocouple, mV, or RTD input ±20 V DC for DC voltage input
- Noise rejection ratio: 40 dB (50/60 Hz) or more in normal mode 120 dB (50/60 Hz) or more in common mode
- Reference junction compensation error:  $\pm 1.0^{\circ}C$  (15 to 35°C)  $\pm 1.5^{\circ}C$  (0 to 15°C, 35 to 50°C)
- Applicable standards: JIS, IEC, DIN (ITS-90) for thermocouples and RTD

#### Loop Power Supply

Supplies power to a two-wire transmitter.

(15 V DC: terminals (14-(15); 24 V DC: terminals (21-(22))

Å resistor (10 to 250  $\Omega$ ) connected between the controller and transmitter converts a current signal into a voltage signal, which is then read via the PV input terminal. Supply voltage: 14.5 to 18.0 V DC, max. 21 mA (provided with a protection circuit against a field short-circuit); 21.6 to 28.0 V DC, max. 30 mA (only for models with 24 V DC loop power supply)

When using the 24 V DC loop power supply of the UT320, keep the operating ambient temperature between 0°C and 40°C.

#### **Retransmission Output**

Either PV, target setpoint, or control output is output. Either the retransmission output or the loop power supply can be used with terminals (4)-(5).

- Number of outputs: 1 (terminals 14-15)
- Output signal: 4-20 mA DC
- Load resistance: 600  $\Omega$  or less
- Output accuracy: ±0.3% of span under standard operating conditions (23±2°C, 55±10% RH, power frequency of 50/60 Hz)

#### **Control Output**

Universal output system, The output type can be selected with the software.

Current output

(Standard type: terminals (6-17); Heating/cooling type: Heating side: terminals (6-17); Cooling side: terminals (4-15)

| Number of outputs | 1 or 2 (two for heating/cooling type),<br>switched between a voltage pulse output<br>and current output. |
|-------------------|--|
| Output signal     | 4-20 mA DC   |
| Load resistance   | 600 $\Omega$ or less   |
| Output accuracy   | ±0.3% of span under standard operating<br>conditions (23±2 ℃, 55±10% RH,<br>power frequency of 50/60 Hz) |

• Voltage pulse output

(Standard type: terminals (6-17); Heating/cooling type: Heating side: terminals (6-17); Cooling side: terminals (4-15)

| Number of outputs | 1 or 2 (two for heating/cooling type),<br>switched between a voltage pulse output and current output.   |
|-------------------|---|
| Output signal     | $\begin{array}{l} \mbox{On-voltage} = \mbox{12 V or more} \ (\mbox{load resistance: 600 } \Omega \ \ \mbox{or more}) \\ \mbox{Off-voltage} = \mbox{0.1 V DC or less} \end{array}$ |
| Resolution        | 10 ms   |

#### Relay contact output

(Standard type: terminals (1-2-3); Heating/cooling type: Heating side: terminals (1-2-3); Cooling side: terminals (4-7))

| Number of outputs | 1 or 2 (two for heating/cooling type)  |  |
|-------------------|--|--|
| Output signal     | Three terminals (NC, NO, and common) /<br>Two terminals  |  |
| Contact rating    | Terminals 1-2-3 :<br>250 V AC or 30 V DC, 3 A (resistance load)<br>Terminal 4-7 :<br>240 V AC or 30 V DC, 1A (resistance load) |  |
| Resolution        | 10 ms  |  |

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#### **Contact Inputs**

- Purpose: Selection between target setpoints or Auto/Man modes, or for other purposes
- Number of inputs: 2
- Input type: Non-voltage contact or transistor open collector input
- Input contact rating: 12 V DC, 10 mA or more
- On/off determination: For non-voltage contact input, contact resistance of 1 k $\Omega$  or less is determined as "on" and contact resistance of 20 k $\Omega$  or more as "off." For transistor open collector input, input voltage of 2 V or less is determined as "on" and leakage current must not exceed 100  $\mu$ A when "off."
- Minimum status detection hold time: About 1 second.

#### **Contact Outputs**

- Purpose: Alarm output, FAIL output, and others
- Number of outputs: 3
- Relay contact rating: 240 V AC/1 A or 30 V DC/1 A (COM terminal is common.) (FAIL output : 1b)

#### **Display Specifications**

- PV display: UT350: 4-digit, 7-segment red LED display, character height of 20 mm UT320: 4-digit, 7-segment red LED display, character height of 12 mm
- Setpoint display: 4-digit, 7-segment red LED display, character height of 9.3 mm (for both UT350 and UT320)
- Status indicating lamps: LEDs

#### Safety and EMC Standards

Safety: Complies with IEC/EN61010-1 (CE), approved by C22.2 No.61010-1, approved by UL508.

Installation category : CAT. II Pollution degree : 2 (IEC/EN61010-1, C22.2 No.61010-1)

Measurement category : I (CAT. I : IEC/EN61010-1)

Rated measurement input voltage : 10V DC max.(across terminals), 300V AC max.(across ground)

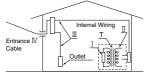
Rated transient overvoltage : 1500V (Note)

Note : It is a value on the safety standard which is assumed by IEC/EN61010-1 in Measurement category I, and is not the value which guarantees an apparatus performance.



This equipment has Measurement category I, therefore do not use the equipment for measurements within Measurement categories II, III and IV.

| Measurement category            |         | Description  | Remarks                                   |  |
|---------------------------------|---------|--|---|--|
| I CAT. I For measurements perfo |         | For measurements performed on circuits not directly connected to MAINS.                    |   |  |
| Π                               | CAT. II | For measurements performed on circuits directly connected to the low voltage installation. | Appliances, portable equipments, etc.     |  |
| I                               | CAT. II | For measurements performed in the building installation.                                   | Distribution board, circuit breaker, etc. |  |
| IV                              | CAT.IV  | For measurements performed at the source of the low-voltage installation.                  | Overhead wire, cable systems, etc.        |  |



 EMC standards: Complies with EN61326, EN61000-3-2, EN61000-3-3 and EN55011 (CE).

AS/NZS 2064 compliant (C-Tick). Class A Group 1.

The instrument continues to operate at a measuring accuracy of within  $\pm 20\%$  of the range during tests.

#### **Construction, Installation, and Wiring**

- Construction: Dust-proof and drip-proof pront panel conforming to IP55. For side-byside close installation the controller loses its dust-proof and drip-proof protection.
- Material: ABS resin and polycarbonate
- Case color: Black
- Weight: About 1 kg or less
- Dimensions: UT350 — 96 (W)  $\times$  96 (H)  $\times$  100 (depth from panel face) mm UT320 — 48 (W)  $\times$  96 (H)  $\times$  100 (depth from panel face) mm
- Installation: Panel-mounting type. With top and bottom mounting hardware (1 each)

- Panel cutout dimensions: UT350 — 92<sup>+0.8</sup><sub>-</sub> (W) × 92<sup>+0.8</sup><sub>-</sub> (H) mm UT320 — 45<sup>+0.6</sup><sub>-</sub> (W) × 92<sup>+0.8</sup><sub>-</sub> (H) mm
- Installation position: Up to 30° upward facing (not designed for facing downward)
- Wiring: M3.5 screw terminals (for signal wiring and power/ground wiring as well)

#### **Power Supply Specifications**

- Power supply: Rated voltage of 100 to 240 V AC (±10%), 50/60 Hz
- Power consumption: Max. 20 VA (8.0 W max.)
- Internal fuse rating: 250 V AC, 1.6A time-lug fuse
- Data backup: Non-volatile memory (can be written to up to 100,000 times)
- Withstanding voltage
  - Between primary terminals\* and secondary terminals\*\*: At least 1500 V AC for 1 minute
  - Between primary terminals\* and grounding terminal: At least 1500 V AC for 1 minute
  - Between grounding terminal and secondary terminals\*\*: At least 1500 V AC for 1 minute
  - Between secondary terminals\*\*: At least 500 V AC for 1 minute
  - Primary terminals indicate power terminals and relay output terminals
  - \*\* Secondary terminals indicate analog I/O signal, voltage pulse output, and contact input terminals
- Insulation resistance: 20  $\text{M}\Omega$  or more at 500 V DC between power terminals and grounding terminal
- Grounding: Class D grounding (grounding resistance of 100  $\Omega$  or less)

#### Signal Isolations

- PV input terminals: Isolated from other input/output terminals. Not isolated from the internal circuit.
- 15 V DC loop power supply terminals: Not isolated from 4-20 mA analog output and voltage pulse control output. Isolated from other input/output terminals and internal circuit.
- 24 V DC loop power supply terminals: Isolated from the 15 V DC loop power supply terminals, 4-20 mA analog output terminals and voltage pulse control output terminals, other I/O terminals and the internal circuitry.
- 4-20 mA analog output terminals (for control output and retransmission): Not isolated between 4-20 mA outputs and from 15 V DC loop power supply and voltage pulse control output. Isolated from other input/output terminals and internal circuit.
- Voltage pulse control output terminals: Not isolated from 4-20 mA outputs and 15 V DC loop power supply. Isolated from other input/output terminals and internal circuit.
- Relay contact control output terminals: Isolated between contact output terminals and from other input/output terminals and internal circuit.
- Contact input terminals: Not isolated between contact input terminals and from communication terminals. Isolated from other input/output terminals and internal circuit.

- Relay contact alarm output terminals: Not isolated between relay contact alarm outputs. Isolated from other input/output terminals and internal circuit.
- RS-485 communication terminals: Not isolated from contact input terminals. Isolated from other input/output terminals and internal circuit.
- Power terminals: Isolated from other input/output terminals and internal circuit.
- Grounding terminals: Isolated from other input/output terminals and internal circuit.

#### **Environmental Conditions**

- Normal operating conditions: Ambient temperature: 0 to 50°C (40°C or less for side-by-side close installation) The operating ambient temperature range is between 0°C and 40°C when the 24 V DC loop power supply of the UT320 is used. Temperature change rate: 10°C/h or less Ambient humidity: 20 to 90% RH (no condensation allowed) Magnetic field: 400 A/m or less Continuous vibration at 5 to 14 Hz: Full amplitude of 1.2 mm or less Continuous vibration at 14 to 150 Hz: 4.9 m/s<sup>2</sup> or less Short-period vibration: 14.7 m/s<sup>2</sup>, 15 seconds or less Shock: 147 m/s<sup>2</sup> or less, 11 ms Installation height: Height above sea level of 2000 m or less Warm-up time: 30 minutes or more after power on
- Transportation and storage conditions: Temperature: -25 to 70°C
   Temperature change rate: 20°C/h or less
   Humidity: 5 to 95% RH (no condensation allowed)
- Effects of changes in operating conditions
  - Effects from changes in ambient temperature:
    - On voltage or thermocouple input,  $\pm 1~\mu\text{V}/^{\circ}\text{C}$  or  $\pm 0.01\%$  of F.S./°C, whichever is larger
    - On RTD input, ±0.05°C/°C (ambient temperature) or less
    - On analog output,  $\pm 0.05\%$  of F.S./°C or less
  - Effects from power supply fluctuation (within rated voltage range)
    - On analog input,  $\pm 1~\mu\text{V}/10$  V or  $\pm 0.01\%$  of F.S./10 V, whichever is larger
    - On analog output,  $\pm 0.05\%$  of F.S./10 V or less

1-13

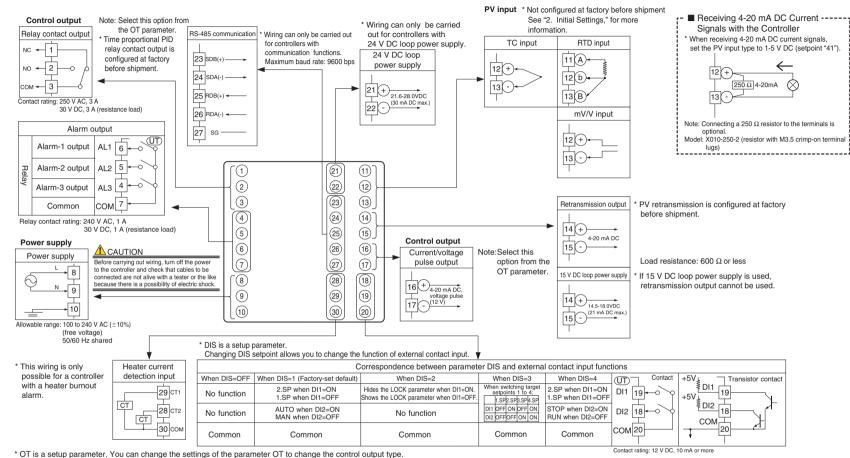
# **1.5 Terminal Wiring Diagrams**



Do not use unassigned terminals as relay terminals.

Terminal wiring diagrams are shown on and after the next page.

### ■ UT350 Standard Type (Model UT350-0□ or UT350-3□) or Heating/Cooling Type (Model UT350-2□)



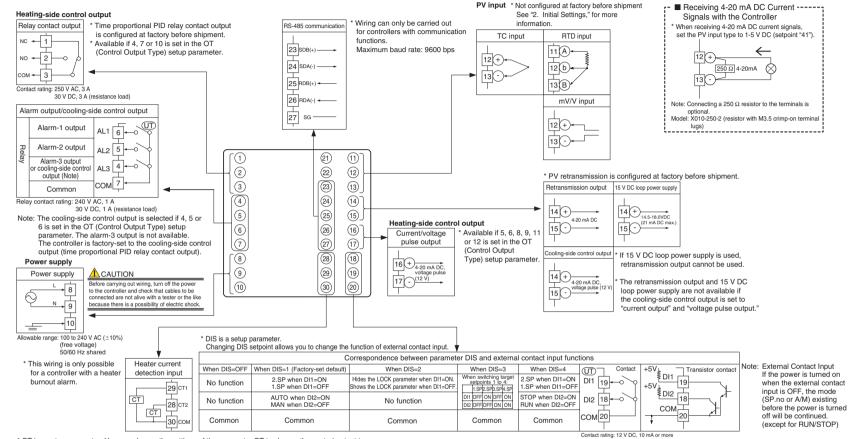
See "2. Initial Settings," for more information.

| Correspondence between parameter OT and control output types  |   |   |  |  |  |  |
|---|---|---|--|--|--|--|
| OT=0 (factory-set default) OT=1 OT=2 OT=3                     |   |   |  |  |  |  |
| Time proportional control<br>Relay output (terminals①, ②and③) | Time proportional control<br>Voltage pulse output (terminals (6) and (7)) | Current output<br>(terminals () and ()) | On-off control<br>Relay output (terminals ①, ②and ③) |  |  |  |

#### Note: External Contact Input

If the power is turned on when the external contact input is OFF, the mode (SP.no or A/M) existing before the power is turned off will be continued. (except for RUN/STOP) Installation>

### ■ UT350 Heating/Cooling Type (Model UT350-2□)

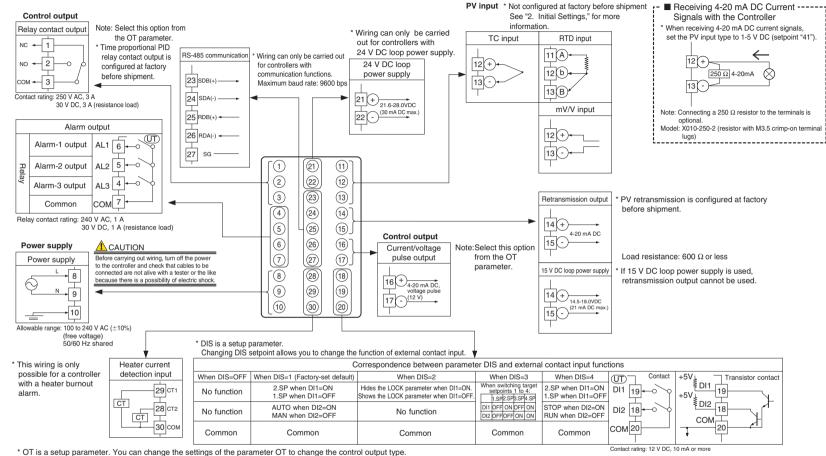


\* OT is a setup parameter. You can change the settings of the parameter OT to change the control output type. See "2. Initial Settings," for more information.

| Correspondence between parameter OT and heating-side/cooling-side output types |   |  |                        |  |  |   |  |  |
|--|---|--|------------------------|--|--|---|--|--|
| OT=4 (factory-set default)   | OT=4 (factory-set default)         OT=5         OT=6         OT=7         OT=8         OT=9         OT=10         OT=11         OT=12 |  |                        |  |  |   |  | OT=12  |
| (terminals(1),(2) and (3))   | Heating side: Voltage pulse output<br>(terminals (ⓑ and ⑦)<br>Cooling side: Relay output<br>(terminals ④ and ⑦)                       | Heating side: Current output<br>(terminals(6)and(7))<br>Cooling side: Relay output<br>(terminals(4)and(7)) | (terminals 1, 2 and 3) | Heating side: Voltage pulse output<br>(terminals (ⓑ and ⑦)<br>Cooling side: Voltage pulse output<br>(terminals (ⓓ and ⑮) | (terminals (16) and (77)<br>Cooling side: Voltage pulse output | Heating side: Relay output<br>(terminals ①, ②and ③)<br>Cooling side: Current output<br>(terminals ④and ⑤) | Heating side: Voltage pulse output<br>(terminals (6) and (7))<br>Cooling side: Current output<br>(terminals (4) and (5)) | Heating side: Current output<br>(terminals (band (7))<br>Cooling side: Current output<br>(terminals (4) and (5)) |

The control output types, "relay output" and "voltage pulse output" shown in the table above refer to those of time proportional control. To change the type to a relay output for on-off control, select "Relay Terminals" and change the setpoint of the proportional band to "0."

### ■ UT320 Standard Type (Model UT320-0□ or UT320-3□) or Heating/Cooling Type (Model UT320-2□)



See "2. Initial Settings," for more information.

| Correspondence between parameter OT and control output types  |   |   |  |  |  |  |
|---|---|---|--|--|--|--|
| OT=0 (factory-set default) OT=1 OT=2 OT=3                     |   |   |  |  |  |  |
| Time proportional control<br>Relay output (terminals①, ②and③) | Time proportional control<br>Voltage pulse output (terminals (6) and (7)) | Current output<br>(terminals () and ()) | On-off control<br>Relay output (terminals ①, ②and ③) |  |  |  |

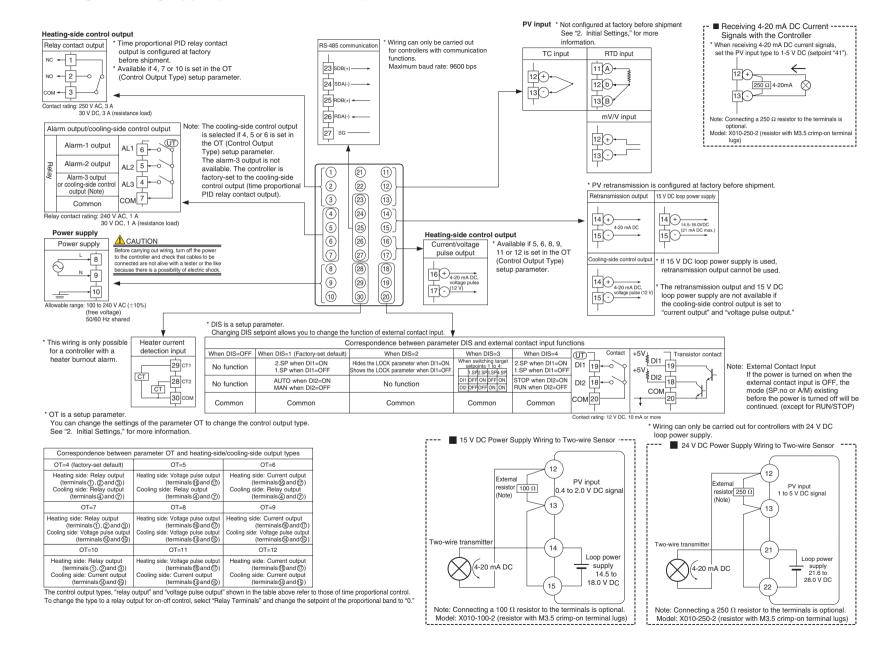
Note: External Contact Input

If the power is turned on when the external contact input is OFF, the mode (SP.no or A/M) existing before the power is turned off will be continued. (except for RUN/STOP)

<u></u>

Installation>

### ■ UT320 Heating/Cooling Type (Model UT320-2□)

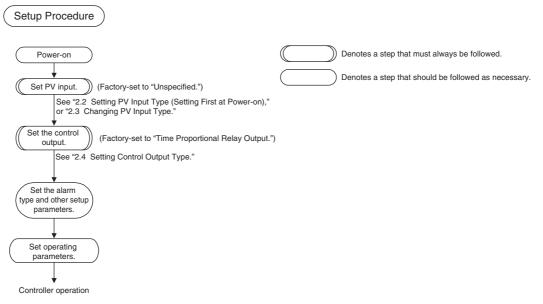


Installation>



# 2. Initial Settings

This chapter describes examples of setting PV input types, control output types, and alarm types. Carrying out settings described herein allows you to perform basic control. Refer to examples of various settings to understand how to set parameters required. Refer to "5.1 Parameter Map" for an easy to understand explanation of setting various parameters. If you cannot remember how to carry out an operation during setting, press the repeated were than 3 seconds. This brings you to the display (operating display) that appears at power-on.



The following explanation of operation for the UT350's panel, shown in the figure, is the same as that of the UT320's panel.

2.1

## **Names and Functions of Front Panel Parts**

| (:<br>ir<br>5. A<br>ir<br>8. L<br>6. L<br>ir<br>7. A | Target setpoint<br>SP) number<br>ndicator lamps<br>Varm<br>ndicator<br>amps<br>.ight-loader<br>nterface<br>VM key<br>SET/ENT key   | Noncess       1. Process         variable (PV)       display         2. Setpoint       display         3. Target setpoint       PV         display       3. Target setpoint         (SP) number       Indicator lamps         indicator       Image         indicator       Image         Image       Setpoint         Setpoint       Setpoint         display       Setpoint         dindicator       Setpoint <t< th=""></t<> |  |
|--|--|---|--|
|  | Name of Part   | Function  |  |
| 1.   | Process variable (PV)<br>display   | Displays PV.<br>Displays a parameter symbol when you set a parameter.<br>Displays an error code (in red) if an error occurs.  |  |
| 2.   | . Setpoint display Displays the setpoint (SP) or the output value (OUT) during operation. Displays the set value of parameters on the parameter setting display.   |   |  |
| 3.   | Target setpoint (SP)       When the SP number currently used for operation is 2, 3 or 4, the respective SP No. indicator lamp lights.         number indicator lamps       When the SP number is 1, the lamp does not light. |   |  |
| 4.   | Status indicatorIs lit in green during manual operation. MAN: Is lit when in manual mode.IampBlinks during auto-tuning.  |   |  |
|  |  |   |  |

| 5. | Alarm indicator lamps  | If any of alarms 1 to 3 occurs, the respective alarm indicator lamp (AL1 to AL3) is lit (in orange).   |
|----|------------------------|--|
| 6. | Light-loader interface | Interface for an adapter cable used when setting and storing parameters from a PC.<br>This requires an optional parameter setting tool.  |
| 7. | A/M key                | Used to switch between the AUTO and MAN modes. Each time you press the key, it switches to the AUTO or MAN mode alternately.   |
| 8. | SET/ENT Key            | Used to switch or register a parameter. Pressing the key for more than 3 seconds allows you to switch<br>between the operating display and the menu for operating parameter setting display alternately.   |
| 9. | ∇and △        keys     | Used to change numerical values. On setting displays for various parameters, you can change target setpoints, parameters, and output values (in manual operation). Pressing the $\bigtriangledown$ key decreases a numerical value, while pressing the $\triangle$ key causes it to increase. You can hold down a key to gradually increase the speed of change. |



The controller automatically returns to the display at the time of power-on (i.e., operating display) if no key is operated for at least one minute.

### Setting of Main Parameters at the Factory before Shipment

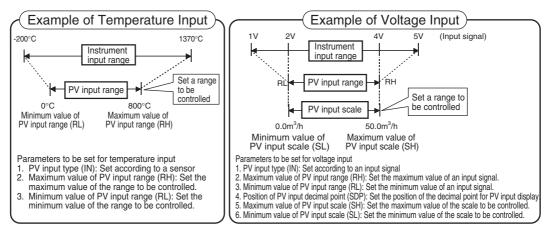
| Item           | Factory-set defaults<br>for standard type<br>controllers              | Factory-set defaults<br>for heating/cooling type controllers |  |
|----------------|---|--|--|
| Control output | Time proportional PID   | Heating side: Time proportional PID relay output (variable)  |  |
|                | relay output (variable)   | Cooling side: Time proportional PID relay output (variable)  |  |
| Control action | Reverse action (variable)   | Not specified  |  |
| PID parameter  | P = 5.0%, I = 240 seconds, D = 60 seconds.                            |  |  |
| Alarm output   | Alarm-1: PV high limit, Alarm-2: PV low limit, Alarm-3: PV high limit |  |  |

## 2.2 Setting PV Input Type (Setting First at Power-on)

# 

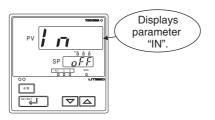
- The controller displays the operating display when the power is turned on. However, if PV input type has not been set, "IN" appears. In this case, first use the key to display the input range code to use, then press the key to register it. Then, set the maximum value (RH) and minimum value (RL) of the PV input range (for voltage input, set the maximum value (SH) and minimum value (SL) of the PV input scale).
- The controller is configured to the initial value of each parameter at the factory before shipment.

First check the initial values shown in "5.2 Lists of Parameters," and change parameter values as necessary.

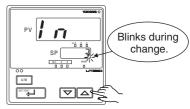


The following operating procedure describes an example of setting the controller to a K-type thermocouple (-199.9°C to 500.0°C) and the measurement range of 0.0°C to 200.0°C.

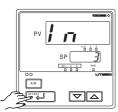
1. Display screen at power-on The parameter "IN" for setting the PV input type appears.



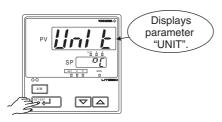
 Press the △ or ▽ key to display the required setpoint. The figure below is an example of the controller set to a K-type thermocouple (-199.9°C to 500.0°C). See "Instrument Input Range Codes."



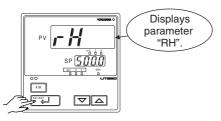
3. Press the setpoint.



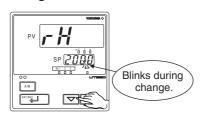
4. Press the *terministic* key once to display the parameter "UNIT" (PV Input Unit).



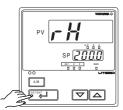
5. Press the Key once to display the parameter "RH" (maximum value of PV input range).



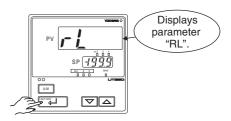
6. Press the △ or ▽ key to display the required setpoint. The figure below shows an example of setting the maximum value of PV input range to 200.0°C.



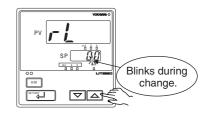
7. Press the setpoint. key once to register the setpoint.



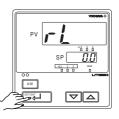
8. Press the Key once to display the parameter "RL" (minimum value of PV input range).



9. Press the △ or ▽ key to display the required setpoint. The figure below shows an example of setting the minimum value of PV input range to 0.0°C.

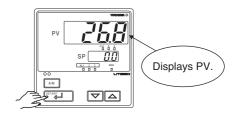


**10.** Press the key once to register the setpoint.



If the type of input is voltage, also configure the PV Input Decimal Point Position (SDP), Maximum Value of PV Input Scale (SH) and Minimum Value of PV Input Scale (SL) that follow this step.

11. To set the type of control output, see steps 7 and later in "2.4 Setting Control Output Type." To finish settings, press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below).



The PV display in the figure above shows the error code for input burnout ( $b_{ab}Ub$ ) if PV input wiring is not yet complete. The error code disappears when you wire the PV input terminals correctly.

### Instrument Input Range Codes

|              |                    | $\downarrow$                   | Select the unit fro  | om the UNIT parameter.   |
|--------------|--------------------|--------------------------------|--|--|
| Input        | Туре               | Instrument Input<br>Range Code | Instrument<br>Input Range  | Measurement Accuracy   |
| Unspecified  |                    | OFF                            | Set the data item PV Input Type "IN" to the OFF option to leave the PV input type undefined. |  |
|              |                    | 1                              | -200 to 1370°C<br>-300 to 2500°F   |  |
|              | к                  | 2                              | -199.9 to 999.9°C<br>0 to 2300°F   |  |
|              |                    | 3                              | -199.9 to 500.0°C<br>-199.9 to 999.9°F   | $\pm$ 0.1% of instrument range $\pm$ 1 digit for temperatures equal to or higher than 0°C  |
|              | J                  | 4                              | -199.9 to 999.9°C<br>-300 to 2300°F  | $\pm 0.2\%$ of instrument range $\pm 1$ digit for temperatures below 0°C   |
|              |                    | 5                              | -199.9 to 400.0°C<br>-300 to 750°F   |  |
|              | Т                  | 6                              | 0.0 to 400.0°C<br>-199.9 to 750.0°F  |  |
|              | в                  | 7                              | 0 to 1800°C<br>32 to 3300°F  | $\pm$ 0.15% of instrument range $\pm$ 1 digit at 400°C or more $\pm$ 5% of instrument range $\pm$ 1 digit at less than 400°C   |
|              | S                  | 8                              | 0 to 1700°C<br>32 to 3100°F  | $\pm$ 0.15% of instrument range $\pm$ 1 digit  |
|              | R                  | 9                              | 0 to 1700°C<br>32 to 3100°F  |  |
| Thermocouple | N                  | 10                             | -200 to 1300°C<br>-300 to 2400°F   | $\pm 0.1\%$ of instrument range $\pm 1$ digit $\pm 0.25\%$ of instrument range $\pm 1$ digit for temperatures below 0°C  |
|              | E                  | 11                             | -199.9 to 999.9°C<br>-300 to 1800°F  |  |
|              | L(DIN)             | 12                             | -199.9 to 900.0°C<br>-300 to 1300°F  | $\pm 0.1\%$ of instrument range $\pm 1$ digit for temperatures<br>equal to or higher than 0°C<br>$\pm 0.2\%$ of instrument range $\pm 1$ digit for temperatures<br>below 0°C |
|              | U(DIN)             | 13                             | -199.9 to 400.0°C<br>-300 to 750°F   |  |
|              | O(Dill)            | 14                             | 0.0 to 400.0°C<br>-199.9 to 750.0°F  |  |
|              | w                  | 15                             | 0 to 2300°C<br>32 to 4200°F  | $\pm$ 0.2% of instrument range $\pm$ 1 digit   |
|              | Platinel 2         | 16                             | 0 to 1390°C<br>32 to 2500°F  | $\pm$ 0.1% of instrument range $\pm$ 1 digit   |
|              | PR20-40            | 17                             | 0 to 1900°C<br>32 to 3400°F  | $\pm 0.5\%$ of instrument range $\pm 1$ digit at 800°C or more No accuracy is guaranteed at less than 800°C  |
|              | W97Re3-<br>W75Re25 | 18                             | 0 to 2000°C<br>32 to 3600°F  | $\pm$ 0.2% of instrument range $\pm$ 1 digit   |
|              | JPt100             | 30                             | -199.9 to 500.0°C<br>-199.9 to 999.9°F   | $\pm$ 0.1% of instrument range $\pm$ 1 digit (Note 1) (Note 2)   |
|              |                    | 31                             | -150.0 to 150.0°C<br>-199.9 to 300.0°F   | $\pm$ 0.2% of instrument range $\pm$ 1 digit (Note 1)  |
| RTD          |                    | 35                             | -199.9 to 850.0°C<br>-300 to 1560°F  | $\pm 0.1\%$ of instrument range $\pm 1$ digit (Note 1) (Note 2)  |
|              | Pt100              | 36                             | -199.9 to 500.0°C<br>-199.9 to 999.9°F<br>-150.0 to 150.0°C                                  |  |
| Otana da u l | 0.445.01/          | 37                             | -199.9 to 300.0°F  | $\pm$ 0.2% of instrument range $\pm$ 1 digit (Note 1)  |
| Standard     | 0.4 to 2 V         | 40                             | 0.400 to 2.000 V   | 4  |
| signal       | 1 to 5 V           | 41                             | 1.000 to 5.000 V   | $\pm 0.1\%$ of instrument range $\pm 1$ digit  |
|              | 0 to 2 V           | 50                             | 0.000 to 2.000 V   | The read-out range can be scaled between -1999 to  |
| DC voltage   | 0 to 10 V          | 51                             | 0.00 to 10.00 V  | 9999.  |
| 0            | -10 to 20 mV       | 55                             | -10.00 to 20.00 mV   | -  |
|              | 0 to 100 mV        | 56                             | 0.0 to 100.0 mV  | <u> </u>   |

Performance in the standard operating condition (at 23±2°C, 55±10%RH, and 50/60Hz power frequency) 

 Note 1: The accuracy is ±0.3°C of instrument range ±1 digit for a temperature range from 0°C to 100°C.

 Note 2: The accuracy is ±0.5°C of instrument range ±1 digit for a temperature range from -100°C to 200°C.

 \* To receive a 4-20 mA DC signal, select a standard signal of 1 to 5 V DC and connect it to a 250 Ω resistor. This resistor

is optional

Model: X010-250-2 (resistor with M3.5 crimp-on terminal lugs)

# 🗥 ΝΟΤΕ

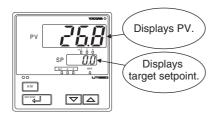
The controller may automatically initialize the registered operating parameter setpoints if any change is made to the data item PV Input Type (IN), Maximum Value of PV Input Range (RH), Minimum Value of PV Input Range (RL), PV Input Decimal Point Position (SDP), Maximum Value of PV Input Scale (SH) or Minimum Value of PV Input Scale (SL). After a change has been made to any of these data items, be sure to verify the registered operating parameter setpoints to ensure that they are correct. If any data item has been changed to its default, set it to a required value.

# 2.3 Changing PV Input Type

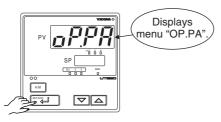
The following operating procedure describes an example of changing the K-type thermocouple (-199.9°C to 500.0°C) to a Pt100 resistance temerature detector (-199.9°C to  $500.0^{\circ}$ C) and setting the measurement range of  $0.0^{\circ}$ C to  $200.0^{\circ}$ C.

| PV input terminal       |          |
|-------------------------|----------|
| Thermocouple/mV/V input | 12-13    |
| RTD input               | 11-12-13 |

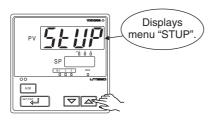
1. Bring the operating display into view (display appears at power on).



2. Press the result is key for more than 3 seconds to call up the menu "OP.PA".



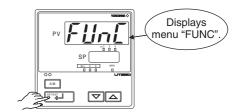
**3.** Press the rightarrow key once to display the menu "STUP".



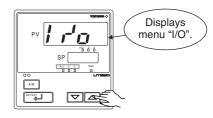
4. Press the strend key once to display the parameter "PWD".



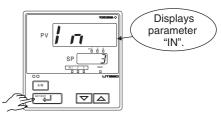
5. Press the strew key once to display the menu "FUNC".



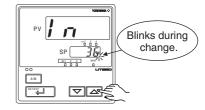
6. Press the 🛆 key once to display the menu "I/O".



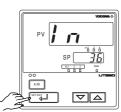
7. Press the Key once to display the parameter "IN" (PV input type).



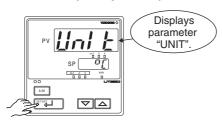
8. Press the △ or ▽ key to display the required setpoint. The figure below is an example of the controller set to a Pt 100 resistance temperature detector (-199.9°C to 500.0°C).



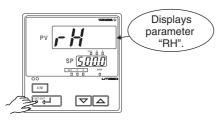
9. Press the register the setpoint.



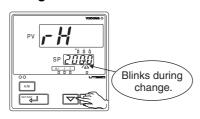
10. Press the Key once to display the parameter "UNIT" (PV input unit).



**11.** Press the Key once to display the parameter "RH" (maximum value of PV input range).



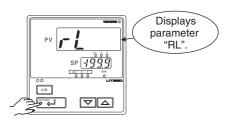
12. Press the △ or ▽ key to display the required setpoint. The figure below shows an example of setting the maximum value of PV input range to 200.0°C.



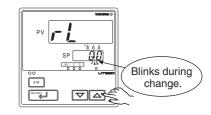
**13.** Press the key once to register the setpoint.



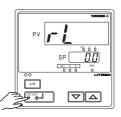
14. Press the Key once to display the parameter "RL" (minimum value of PV input range).



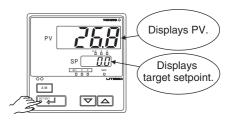
15. Press the △ or ▽ key to display the required setpoint. The figure below shows an example of setting the minimum value of PV input range to 0.0°C.



**16.** Press the key once to register the setpoint.



17. Press the <u>seconds</u>. This returns you to the display shown at power-on (figure below).



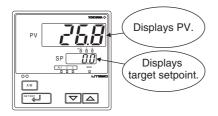
The PV display in the figure above shows the error code for input burnout (ball b)if PV input wiring is not yet complete. The error code disappears when you wire the PV input terminals correctly.

# 2.4 Setting Control Output Type

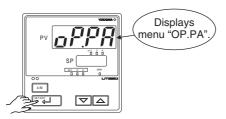
The following operating procedure describes an example of changing time proportional PID relay output (0: factory-set default) to current output (2).

| Control output terminal Values in parentheses are setpoints      |  |  |
|--|--|--|
|  |  |  |
| Time proportional PID relay (0)/on-off(3) output                 |  |  |
| Current (2)/time proportional PID voltage pulse (1) output       |  |  |
| For details on the heating/cooling control output terminals, see |  |  |
| "1.5 Terminal Wiring Diagrams."                                  |  |  |

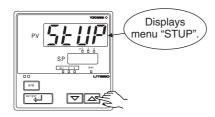
1. Bring the operating display into view (display appears at power on).



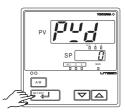
2. Press the result is the for more than 3 seconds to call up the menu "OP.PA".



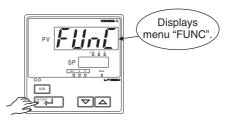
**3.** Press the rightarrow key once to display the menu "STUP".



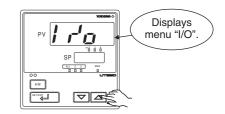
4. Press the *terministic* key once to display the parameter "PWD".



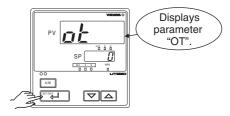
5. Press the result key once to display the menu "FUNC".



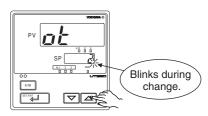
6. Press the 🛆 key once to display the menu "I/O".



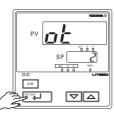
7. Press the real times to display the parameter "OT" (control output type).



8. Press the or key to display the required setpoint. The figure below shows an example of setting to current output (4 to 20 mA DC).



9. Press the setpoint. key once to register the setpoint.



**10.** Press the <u>main</u> key for <u>more than 3 seconds</u>. This returns you to the display shown at power-on (figure below).



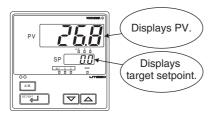
# 2.5 Changing Alarm Type

The following operating procedure describes an example of changing alarm-1 (factory-set default: PV high limit alarm) to PV low limit alarm.

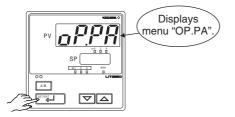
When you have changed alarm type, the alarm setpoint will be initialized; set the alarm setpoint again.

| Alarm output terminals        | Factory-set defaults   |
|-------------------------------|------------------------|
| Alarm-1 (terminal numbers 6-7 | ) )PV high limit alarm |
| Alarm-2 (terminal numbers 5-7 | )PV low limit alarm    |
| Alarm-3 (terminal numbers 4-7 | ) )PV high limit alarm |

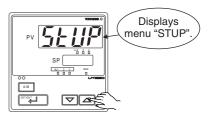
1. Bring the operating display into view (appears at power-on).



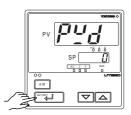
2. Press the series key for more than 3 seconds to call up the menu "OP.PA".



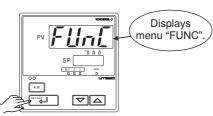
**3.** Press the  $\bigtriangleup$  key once to display the menu "STUP".



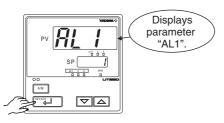
4. Press the Key once to display the parameter "PWD".



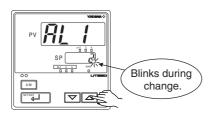
5. Press the street key once to display the menu "FUNC".



6. Press the result imes to display the parameter "AL1" (alarm-1 type).



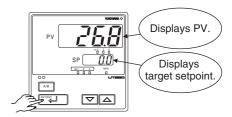
7. Press the △ or ▽ key to display the required setpoint. The figure below shows an example of setting PV low limit alarm.



8. Press the *terminal* key once to register the setpoint. You can take the same steps for alarm-2 type (AL2), and alarm-3 type (AL3) that are displayed after this.



9. Press the <sup>□</sup> key for <u>more than 3 sec-</u> <u>onds</u>. This returns you to the display shown at power-on (figure below).



**10.** When setting an alarm setpoint, see "3.4 Setting Alarm Setpoints."

### ■ List of Alarm Types

The table below shows the alarm types and alarm actions.

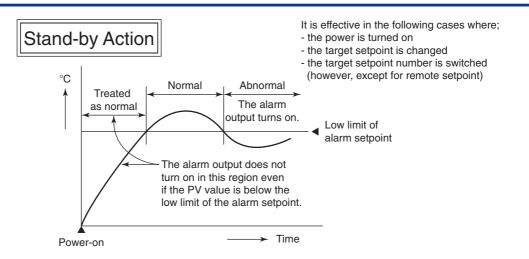
In the table, codes 1 to 10 are not provided with stand-by actions, while codes 11 to 20 are provided with stand-by actions.

|  | Alarma antian   | Alarm ty                                | pe code                                |   | Alerra estien   | Alarm ty                                | vpe code                               |
|--|---|---|--|---|---|---|--|
| Alarm type                                       | Alarm action<br>"Open/close" shows status of relay contact,<br>and "lit" and "unlit" shows status of lamp   | Contact<br>closes<br>if alarm<br>occurs | Contact<br>opens<br>if alarm<br>occurs | Alarm type                                      | Alarm action<br>"Open/close" shows status of relay contact,<br>and "lit" and "unlit" shows status of lamp | Contact<br>closes<br>if alarm<br>occurs | Contact<br>opens<br>if alarm<br>occurs |
| No alarm   |   | O                                       | FF                                     |   | Hysteresis  | /                                       |  |
| PV high limit                                    | Open (unlit)<br>PV Alarm setpoint   | 1<br>11                                 |  | De-energized<br>on deviation low<br>limit alarm | Open (lit)<br>Deviation<br>setpoint<br>Target SP  |   | 6<br>16                                |
| PV low limit                                     | Hysteresis<br>Closed (lit) Open (unlit)<br>Alarm setpoint PV  | 2<br>12                                 |  | Deviation high<br>and low limits                | Hysteresis<br>Closed<br>(lift)<br>Deviation setpoint<br>Target SP   | 7<br>17                                 |  |
| Deviation high<br>limit                          | Open (unlit)<br>PV<br>Target SP   | 3<br>13                                 |  | Deviation within<br>high and low<br>limits      | Hysteresis<br>Open<br>(unlit)<br>Deviation setpoint<br>Target SP  | 8<br>18                                 |  |
| Deviation low<br>limit                           | Hysteresis<br>Closed (lit)<br>Deviation setpoint<br>Target SP   | 4<br>14                                 |  | De-energized<br>on PV high limit                | Closed<br>(unlit)<br>PV Alarm setpoint  |   | 9<br>19                                |
| De-energized on<br>deviation high<br>limit alarm | Closed<br>(unlit)<br>PV<br>Closed<br>PV<br>Closed<br>PV<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed<br>Closed |   | 5                                      | De-energized<br>on PV low limit                 | Open (lit)<br>Alarm setpoint  |   | 10<br>20                               |
| Fault diagnosis output (Note 1)                  | Fault diagnosis output  | 21                                      |  | Heater<br>burnout alarm 1                       |   | 24                                      |  |
| FAIL output<br>(Note 2)                          | The controller stops when in a FAIL state.<br>The control output is set to "OFF" or "0%"<br>and alarm output is set to "OFF".   |   | 22                                     | Heater  | Heater burnout alarms 1 and 2   |   |  |
| Sensor grounding<br>alarm                        | Sensor grounding alarm  | 23                                      |  | burnout alarm 2                                 |   | 25                                      |  |
| SP high<br>limit                                 | Hysteresis<br>Closed (lit)<br>Open (unlit)<br>SP Alarm setpoint   | 28                                      |  | Output high<br>limit                            | Open (unlit)<br>Output value  | 30                                      |  |
| SP low<br>limit                                  | Hysteresis<br>Closed (lit)<br>Open (unlit)<br>Alarm setpoint SP   | 29                                      |  | Output low<br>limit                             | Hysteresis<br>Closed (lit)<br>Alarm setpoint Output value   | 31                                      |  |

Note 1: The fault diagnosis output turns on in case of input burnout, A/D converter failure, or reference junction compensation (RJC) failure.

The control output in case of input burnout or A/D converter failure is set to the value of the PO (Preset Output Value) setup parameter. In case of RJC failure, the controller continues control under the condition of "RJC = OFF".

Note 2: The FAIL output is on during normal operation and turns off in case of failure.



# 2.6 Description of Multiple Setpoints and PID

The UT350/UT320 controllers have a maximum of four target setpoint (SP) parameters and has PID for each of these setpoints. The following shows the correspondence between the target setpoint numbers (SP.NO), target setpoints (SP), and PID parameters.

For example, if you have set "2" to the target setpoint number (SP.NO), the control parameters available are target setpoint (2.SP), proportional band (heating-side proportional band) (2.P), integral time (heating-side integral time) (2.I), derivative time (heating-side derivative time) (2.D), cooling-side proportional band (2.Pc), cooling-side integral time (2.Ic), and cooling-side derivative time (2.Dc).

To use multiple target setpoints, see the table below to check the corresponding parameters.

| Target setpoint   | Target           |   |  | PID pa   | rameter                              |                            |                              |
|-------------------|------------------|---|--|--|--------------------------------------|----------------------------|------------------------------|
| number<br>(SP.NO) | setpoint<br>(SP) | Proportional<br>band<br>(heating-side<br>proportional band) | Integral time<br>(heating-side<br>integral time) | Derivative time<br>(heating-side<br>derivative time) | Cooling-side<br>proportional<br>band | Cooling-side integral time | Cooling-side derivative time |
| SP.NO=1           | 1.SP             | 1.P   | 1.1  | 1.D  | 1.Pc                                 | 1.lc                       | 1.Dc                         |
| SP.NO=2           | 2.SP             | 2.P   | 2.1  | 2.D  | 2.Pc                                 | 2.lc                       | 2.Dc                         |
| SP.NO=3           | 3.SP             | 3.P   | 3.1  | 3.D  | 3.Pc                                 | 3.lc                       | 3.Dc                         |
| SP.NO=4           | 4.SP             | 4.P   | 4.1  | 4.D  | 4.Pc                                 | 4.lc                       | 4.Dc                         |

# 3. **Operations**

This chapter describes key entries for operating the controller. For operations using external contact inputs, see "1.5 Terminal Wiring Diagrams." If you cannot remember how to carry out an operation during setting, press the result is key for more than 3 seconds. This brings you to the display (operating display) that appears at power-on.

# 

Do not use the instrument generating strong magnetic field such as radio equipment and the like near the controller. This may cause the fluctuation of the PV value.

## 3.1 Monitoring-purpose Operating Displays Available during Operation

The monitoring-purpose operating displays available during operation are roughly classified into two groups depending on the types of controller. One group is operating displays for a standard controller and the other group is operating displays for a heating/cooling controller.

## Operating Displays for a Standard Controller

#### • SP Display

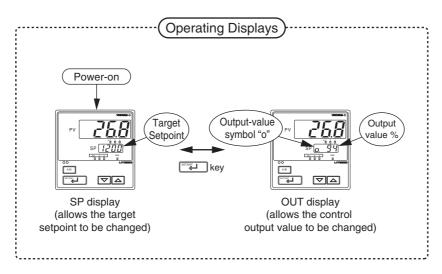
The PV input value appears on the PV display.

The target setpoint (1.SP) appears on the Setpoint display.

#### • OUT Display

The PV input value appears on the PV display.

The control output value (OUT) appears on the Setpoint display.



## Operating Displays for a Heating/Cooling Controller

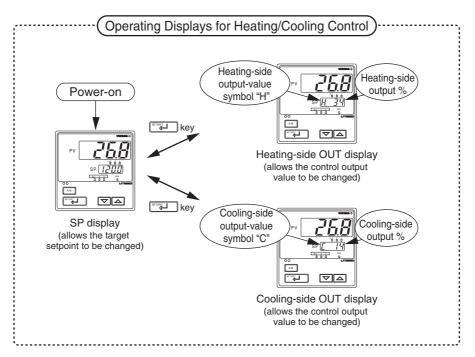
#### • SP Display

The PV input value appears on the PV display. The target setpoint (1.SP) appears on the Setpoint display.

### • Heating/Cooling OUT Display

The PV input value appears on the PV display.

The heating (H) and cooling (C) sides control output values appears on the Setpoint display.



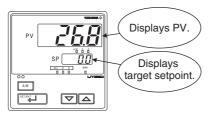
# 3.2 Setting Target Setpoint (SP)

The following operating procedure describes an example of setting 120.0 to a target setpoint. In automatic operation, the controller starts control using set target setpoints.



When the target setpoint is set through communication, the target setpoint cannot be changed by keystroke.

**1.** Bring the operating display into view (display appears at power on).



2. Press the  $\bigtriangleup$  or  $\bigtriangledown$  key to display the required setpoint.



3. Press the setpoint.



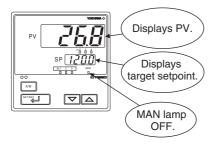
# 3.3 Performing/Canceling Auto-tuning

Auto-tuning should be carried out after setting a target setpoint (SP). Make sure the controller is in automatic operation mode (AUTO) and running state (RUN) before carrying out auto-tuning. See "3.8 Switching between AUTO and MAN," to change to AUTO and "3.7 Switching between Run and Stop," to change to Run.

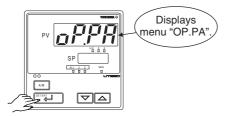
# 

When on-off control is being used, auto-tuning cannot be carried out. Moreover, do not perform auto-tuning when controlling any of the following processes.

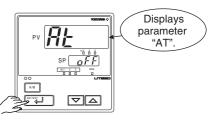
- Control processes with quick response such as flow control or pressure control
- Processes where even temporary output on/off results in inconvenience
- Processes where a large output change at control element results in inconvenience
- Processes where variations in PV may exceed an allowable range, adversely affecting product quality
- 1. Bring the operating display into view (display appears at power on).



2. Press the result key for more than 3 seconds to call up the menu "OP.PA".



**3.** Press the street key five times to display the parameter "AT".



4. Press the  $\bigtriangleup$  or  $\bigtriangledown$  key to display the required setpoint. Tuning for 1.SP is AT = 1.



To cancel auto-tuning, set AT = OFF.

5. Press the register the setpoint. (This starts auto-tuning.) If the register the setpoint. (This starts auto-tuning.) If the register the set of the starts auto-tuning will be cancelled. In this case, PID contains the value existing before auto-tuning.



6. During auto-tuning, the panel indications become as shown below.



Auto-tuning is complete when the MAN lamp goes off.

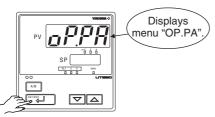
# 3.4 Setting PID Manually

If you know the values to be set or if suitable PID constants cannot be obtained by autotuning, follow the procedure below to set values.

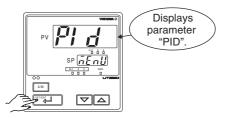
**1.** Bring the operating display into view (display appears at power on).



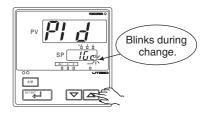
2. Press the set in the menu "OP.PA".



3. Press the everal times to display the parameter "PID".



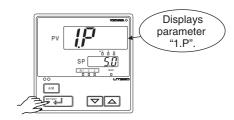
**4.** Press the  $\bigtriangleup$  key once to display "1Gr".



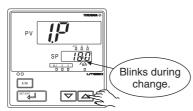
5. Press the setpoints.



6. Press the *terminal* key once to display the parameter "1.P" (proportional band for 1.SP).



7. Press the riangle or riangle key to display the required setpoint.



8. Press the key once to register the setpoint.



The same steps can be used for integral time (1.I) and derivative time (1.D) that are displayed after this.

The PID parameter numbers set in step 4. should be set as follows: In case of PID for 1.SP, PID = 1Gr

In case of PID for 2.SP, PID = 2Gr In case of PID for 3.SP, PID = 3Gr In case of PID for 4.SP, PID = 4Gr

9. Press the <sup>™™</sup> key for <u>more than 3 sec-</u> <u>onds</u>. This returns you to the display shown at power-on (figure below).

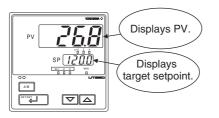


## 3.5 Setting Alarm Setpoints

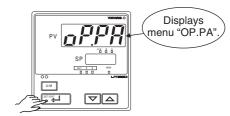
The following operating procedure describes an example of setting 160.0 to alarm-1 setpoint. Check alarm type before setting the alarm setpoint. To change the type of alarm, see "2.5 Changing Alarm Type."

| Alarm output terminals         | Factory-set defaults |
|--------------------------------|----------------------|
| Alarm-1 (terminal numbers 6-7) | PV high limit alarm  |
| Alarm-2 (terminal numbers 5-7) | PV low limit alarm   |
| Alarm-3 (terminal numbers ④-⑦) | PV high limit alarm  |

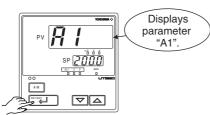
1. Bring the operating display into view (display appears at power on).



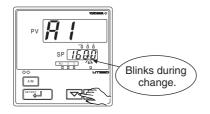
2. Press the series key for more than 3 seconds to call up the menu "OP.PA".



3. Press the real key twice to display the parameter "A1".



4. Press the △ or ▽ key to display the required setpoint.



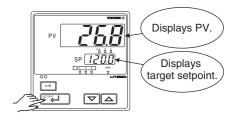
5. Press the setpoint. key once to register the setpoint.



Also configure the Alarm-2 Setpoint (A2) and Alarm-3 Setpoint (A3) parameters that follow this step.

6. Press the two for more than 3 seconds.

This returns you to the display shown at power-on (figure below).



# 3.6 Selecting Target Setpoint Numbers (SP.NO)

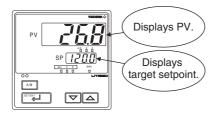
The following operating procedure describes an example of changing a target setpoint number (SP.NO) from 1 to 2.



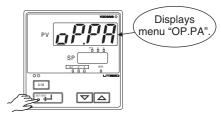
If a target setpoint number has been switched using contact input, when the contact input is on, that number cannot be selected by keystroke.

When using target setpoint ramp setting function, PV tracking works if the target setpoint number is switched.

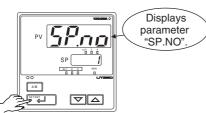
1. Bring the operating display into view (display appears at power on).



2. Press the key for more than 3 seconds to call up the menu "OP.PA".



**3.** Press the several times to display the parameter "SP.NO".



**4.** Press the  $\bigtriangleup$  or  $\bigtriangledown$  key to display the required setpoint.



5. Press the setpoint. key once to register the setpoint.



6. Press the <sup>□</sup> key for <u>more than 3 sec-</u> <u>onds</u>. This returns you to the display shown at power-on (figure below).



# 3.7 Switching between Run and Stop

Switching between the RUN and STOP states can be performed only using external contact input.

When the controller is shipped from the factory, it is configured so that switching between the RUN and STOP states cannot be performed. To make the switching possible, configure the DIS setup parameter as "DIS = 4".

| (18)<br>(20) | Start of operation when OFF |
|--------------|-----------------------------|
| (18)<br>(20) | Stop of operation when ON   |

When the controller is stopped, input and outputs are as follows:

| PV input       | Displays PV.                                  |
|----------------|---|
| Control output | Preset output value (factory-set default: 0%) |
| Alarm output   | ON in the event of an alarm                   |

When the controller is stopped, control output display is "5EDP."

# 3.8 Switching between AUTO and MAN

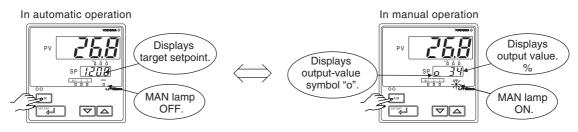
# 

If AUTO and MAN have been switched using contact input, when the contact input is ON, switching between AUTO and MAN cannot be achieved by keystroke.

1. Bring the operating display into view (display appears at power on).



# 2. Each time you press the *M* key on the front panel of the instrument, AUTO and MAN is switched alternately.

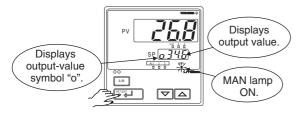


## 3.9 Manipulating Control Output in Manual Operation

Control output cannot be changed if the controller is stopped. In this case, the preset output value (setup parameter PO) will be output.

A control output value is linked with a display value changed using the  $\bigtriangledown$  or  $\bigtriangleup$  key. Note that the control output changes as displayed without requiring the key.

**1.** Bring manual operating display into view. For switching to manual operation, see "3.8 Switching between AUTO and MAN."



Press the △ or ▽ key to change a control output value. You don't need to press the <sup>□</sup> key.



### Manipulating the Control Output during Heating/Cooling Control

Either of the following two displays appears when the mode is switched to MAN during heating/cooling control.

Heating-side OUT display



Cooling-side OUT display

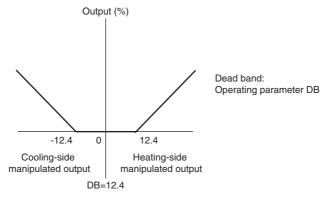


#### Controller Behavior and Control Output Manipulation when the Dead Band is Positive

The following is an example when the DB parameter is set at 12.4%.

If you hold down the  $\bigtriangledown$  key with the heating-side output under manipulation (i.e., coolingside output C = 0.0%), the heating-side output (H =) decreases. Consequently, both the heating-side and cooling-side outputs change to 0.0%. If you keep the  $\boxdot$  key held down longer, you enter the state of manipulating the cooling-side output, and its value begins to increase.

Inversely, if you hold down the  $\bigtriangleup$  key with the cooling-side output under manipulation (i.e., heating-side output H = 0.0%), the cooling-side output (C =) decreases. Consequently, both the heating-side and cooling-side outputs go to 0.0%. If you keep the  $\bigtriangleup$  key held down longer, you enter the state of manipulating the heating-side output, and its value begins to increase.



Change in manipulated output when the dead band is positive



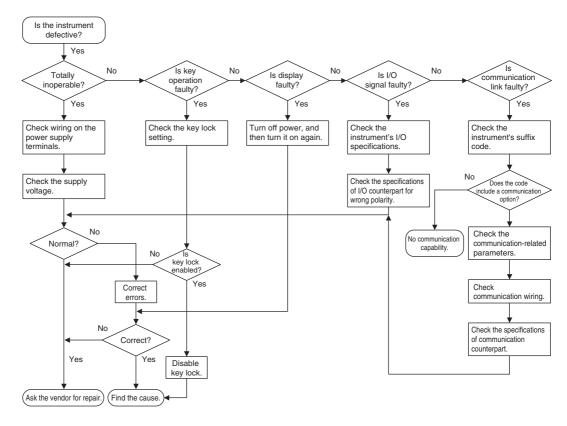
# 4. Troubleshooting and Maintenance

# 4.1 Troubleshooting

## ■ Troubleshooting Flow

If the operating display does not appear after turning on the controller's power, follow the measures in the procedure below.

If a problem appears complicated, contact our sales representative.





Take note of the parameter settings when asking the vendor for repair.

### Errors at Power on

The following table shows errors that may be detected by the fault diagnosis function when the power is turned on.

| Error indication<br>(on PV display unit) | Description<br>of error  | PV                                    | Control<br>output                     | Alarm<br>output                       | Retransmission<br>output              | Communi-<br>cation | Remedy   |  |
|--|--------------------------|---------------------------------------|---------------------------------------|---------------------------------------|---------------------------------------|--------------------|--|--|
| £000 (E000)                              | Faulty RAM               | None                                  |                                       |                                       |                                       | Ctopped            |  |  |
| E00 / (E001)                             | FUU / (E001) Faulty ROM  |                                       | 0% or less<br>or OFF                  | OFF                                   | 0% or less                            | Stopped            | Faulty   |  |
| £002 (E002)                              | System data error        | 0%                                    |                                       |                                       | 0%                                    |                    | Contact us   |  |
| PV decimal point blinks.                 | Faulty calibration value | Normal action<br>(out of<br>accuracy) | Normal action<br>(out of<br>accuracy) | Normal action<br>(out of<br>accuracy) | Normal action<br>(out of<br>accuracy) | Normal             | for repair.  |  |
| <i>ЕЧПП</i> (Е400)                       | Parameter error          | 0%                                    | Preset value<br>output                | OFF                                   | 0%                                    | action             | Check and set<br>the parameters,<br>as they have<br>been set to the<br>limited values. |  |

## Possible Errors during Operation

The following shows possible errors occurring during operations.

| Error indication<br>(on PV display unit)                     | Description<br>of error                            | PV   | Control<br>output         | Alarm<br>output | Retransmis-<br>sion output | Commu-<br>nication | Remedy  |
|--|--|--|---------------------------|-----------------|----------------------------|--------------------|---|
| Displays "RJC"<br>and PV<br>alternately                      | RJC error  | Measured<br>with RJC=OFF   | Normal action             | Normal action   | Normal action              | Normal action      | Faulty<br>Contact us for repair.  |
| PV value blinks.   | EEPROM<br>error                                    | Normal action  | Normal action             | Normal action   | Normal action              | Normal action      | Faulty<br>Contact us for repair.  |
| <i>Е∃∏</i> [[ (E300)   | A/DC error   | 105%   | Preset<br>value<br>output | Normal action   | Normal action              | Normal action      |   |
| <i>b.o.Uと</i> (B.OUT)  | PV burnout<br>error                                | Dependent on the BSL<br>parameter<br>Up-scale: 105%<br>Down-scale: -5% | Preset<br>value<br>output | Normal action   | Normal action              | Normal action      | Check wires and sensor.   |
| ឲដូក(OVER) or<br>- ឲូដូក(-OVER)                              | Excessive PV<br>Out of -5 to<br>105%               | -5% or 105%  | Normal action             | Normal action   | Normal action              | Normal action      | Check process.  |
| <i>Е 2 [] []</i> (E200)                                      | Auto-tuning<br>failure<br>(Time-out)               | Normal action  | Normal action             | Normal action   | Normal action              | Normal action      | Check process. Press<br>any key to erase error<br>indication.                                     |
| SP decimal<br>point blinks.<br>(on setpoint<br>display unit) | Faulty<br>communi-<br>cation line                  | Normal action  | Normal action             | Normal action   | Normal action              | Normal action      | Check wires and<br>communication parameters,<br>and make resetting.<br>Recovery at normal receipt |
| All indications off  | Runaway (due<br>to defective<br>power or<br>noise) | None   | 0% or less<br>or OFF      | OFF             | 0% or<br>less              | Stopped            | Faulty if power off/on does<br>not reset start the unit.<br>Contact us for repair.                |
| All indications off  | Power off  | None   | 0%                        | OFF             | 0%                         | Stopped            | Check for abnormal power.   |

### ■ If a Power Failure Occurs during Operation

#### Momentary Power Failures shorter than 20 ms

The controller is not affected at all and continues normal operation.

#### Power Failures of 20 ms or longer

- The alarm function of the controller continues to work normally. (Alarms with the stand-by feature temporarily return to their stand-by state, however.)
- Setting parameters that have already been configured retain their settings.
- Auto-tuning is cancelled.
- After recovery from a power failure, control action resumes in the same mode as the one before the occurrence of the power failure. The control output begins with the preset output value.

#### Troubleshooting when the Controller Fails to Operate Correctly

If your control tasks are not successful, check the preset parameters and controller wiring before concluding the controller to be defective. The following show some examples of troubleshooting you should refer to in order to avoid the possibility of other problems.

#### • The Controller does not Show the measured input (PV).

- The UT350/UT320 controllers have a universal input.
  - The type of PV input can be set/changed using the parameter "IN". At this point, the controller must be wired correctly according to the selected type of PV input. Check the wiring first if the controller fails to show the correct PV. To do this, refer to "2. Initial Settings."

With the parameters "RH", "RL", "SDP", "SH" and "SL", it is possible to scale the input signal and change its number of decimal places. Also check that these parameters are configured correctly.

# • The Controller does not Provide any Control Output or the Control Output does not Change at all.

- The UT350/UT320 controllers have a universal output. The type of control output can be set/changed using the parameter "OT". At this point, the controller must be wired correctly according to the selected type of control output. Check the wiring first if the controller provides no control output. To do this, refer to "1.5 Terminal Wiring Diagrams." With the parameters "OH" and "OL", it is possible to set/change the high and low limits of control output. The control output may not change at all, however, because of
- The control output can only be changed when the controller is in the MAN mode. If the MAN lamp is off (i.e., the controller is in the AUTO mode), you cannot change the control output using key operation.

restrictions on these parameters. Also check the restrictions on these parameters.

#### The control output does not change soon after the target setpoint (SP) has been changed.

 If this happens, check the setpoint of the parameter "C.MD". In cases where fixedpoint control is selected as the PID control mode (C.MD = 1), tracking based on the Iterm works to prevent the control output from changing suddenly even if the target setpoint SP is varied.

The control output therefore may appear to be working incorrectly at first; however it gradually adapts itself to the new target setpoint.

## 4.2 Maintenance

This section describes the cleaning and maintenance of the UT350/UT320.

## 4.2.1 Cleaning

The front panel and operation keys should be gently wiped with a dry cloth.



Do not use alcohol, benzine, or any other solvents.

## 4.2.2 Replacing Brackets

When the brackets are broken or lost, purchase the following brackets for replacement.

| Target Model Part No. |         | Sales Unit                                |
|-----------------------|---------|---|
| UT350                 | T9115NL | A large bracket and small bracket in pair |
| UT320                 | T9115NK | Two small brackets in pair                |

#### **SEE ALSO**

"1.2 How to Install," for how to replace brackets.

## 4.2.3 Attaching Terminal Cover

When a terminal cover is necessary, purchase the following part.

| Target Model | Part No. | Sales Unit |
|--------------|----------|------------|
| UT350        | T9115YD  | 1          |
| UT320        | T9115YE  | 1          |

## Attaching Terminal Cover

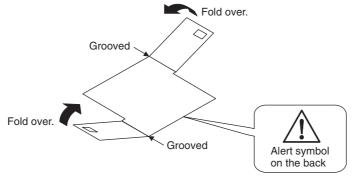
The procedure for attaching the terminal cover is as follows.



Do not touch the terminals on the rear panel when power is being supplied to the controller. Doing so may result in electric shock.

Before attaching the terminal cover, turn off the source circuit breaker and use a tester to check that the power cable is not conducting any electricity.

**1.** Before attaching the terminal cover, fold it once or twice so that the side which has the "Handle With Care" symbol ( $\underline{\wedge}$ ), is on the outside.

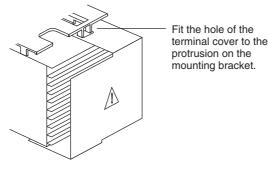


Folding Direction of Terminal Cover



Do not fold the terminal cover the wrong way, doing so not only reduces the cover's strength but may also cause the hinge to crack, thereby disabling attachment.

2. With the cover properly folded, fit its top and bottom holes to the protrusions of the mounting brackets.



**Attaching Terminal Cover** 

## 4.2.4 Replacing Parts with a Limited Service Life

The following UT350/UT320 parts have a limited service life. The service life given in the table assume that the controller is used under normal operating conditions.

| Part                            | Service life   |
|---------------------------------|--|
| Aluminum electrolytic condenser | About 10 years (rated)                                       |
| EEPROM                          | About 100,000 times of writings                              |
| Alarm output relays             | About 100,000 more ON-OFF operations or with resistance load |
| Control output relays           | About 100,000 more ON-OFF operations or with resistance load |

If any of these parts, except control output relays, cause a controller failure due to deterioration, contact your dealer for replacement at your cost.

#### SEE ALSO

"4.2.5 Replacing Control Output Relays," for how to replace the control output relays.

#### **Replacing Control Output Relays** 4.2.5

This subsection describes how to replace the control output relays.

Since inspection is needed in case parts are replacement will be carried out by a YOKOGAWA engineer or an engineer certified by YOKOGAWA. When replacement is required, contact your nearest YOKOGAWA dealer.

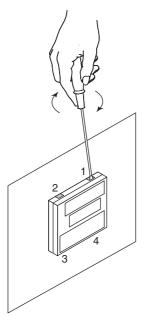


Always turn off the power before starting the work in order to avoid electric shock.

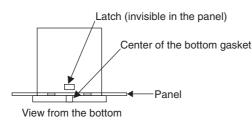
Do not pull out the internal unit for any other purpose other than to replace the control output relays.

1. Insert a flat-blade screwdriver (tip width of 6 mm is recommended) into the opening with the tip in parallel with the front panel, and then turn the screwdriver gently. Take this procedure to four openings 1, 2, 3 and 4 (see the figure below) on the upper and lower parts of the bezel, in order.

The bezel slightly moves forward from the housing.

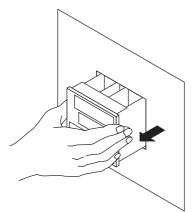


2. Push up the center of the bottom gasket of bezel by a finger to release the latch.



3. Insert the screwdriver into the four openings and flip the tip forward to move the bezel more forward.

**4.** Hold the bezel and pull it along with the internal unit out of the housing. (Note) Be careful not to damage the RJC sensor.

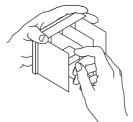


5. The location and number of the relays differ depending on the model code of the UT350/ UT320.

Confirm the location of the control output relay to be replaced before pulling out the relay.



6. Pull out the relay to be replaced. The control output relays are easy to remove and mount, since they are connected via a socket onto the print boards.

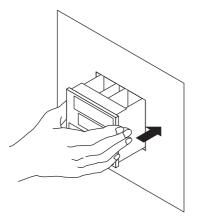


Insert the new relay in the socket. Use the following relay.

| Manufacturer | OMRON               |
|--------------|---------------------|
| Model        | G6B-2114P-FD-US-P6B |
| Power supply | 12 V DC             |

7. Insert the internal unit into the housing.

Apply power to the controller and confirm that the initial operating display is shown. If the operating display is not shown properly, turn off the controller and pull out the internal unit. Then, insert it into the housing again.

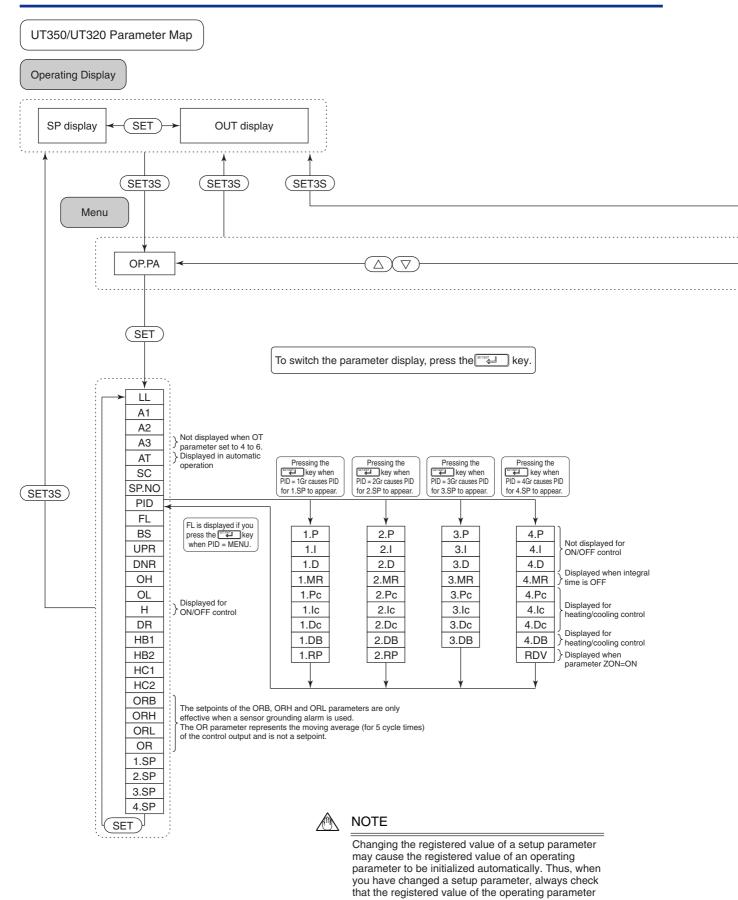


This completes replacement of the control output relay.

# 5. Parameters

This chapter contains a parameter map as a guideline for setting parameters, and lists of parameters for recording User Settings.

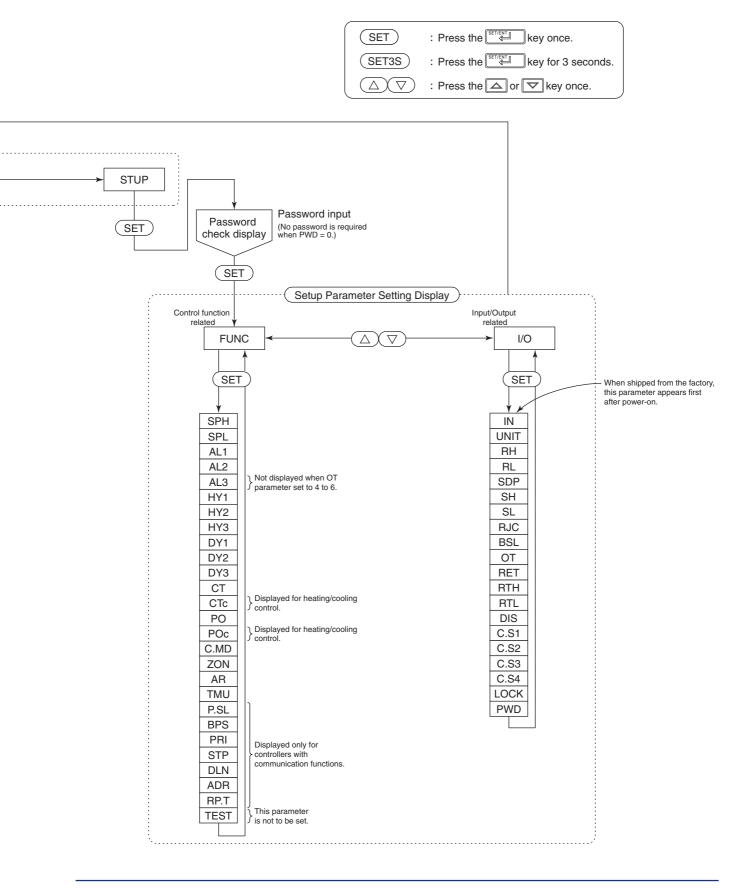
# 5.1 Parameter Map



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is appropriate. If it is initialized to default, reset it to

the required value.



## 5.2 Lists of Parameters

- \* Parameters relating to PV or setpoints should all be set in real numbers. For example, use temperature values to define target setpoints and alarm setpoints for temperature input.
- \* The "User Setting" column in the table is provided for the customer to record setpoints.
- \* The column "Target Item in CD-ROM" in the table provides references from User's Manual (Reference) (CD-ROM version) which describes items in more detail and items that are not contained in this manual.
- \* Numbers in () are the parameter setpoints that apply when the communication function is used. ex. OFF (0), ON (1)

### Operating Parameters

| Parameter<br>Symbol     | Name of Parameter                       | Setting Range and Description  | Initial Value   | User Setting | Target Item<br>in CD-ROM |
|-------------------------|---|--|---|--------------|--------------------------|
|                         | LL communication<br>interface selection | OFF (0): Communication is carried out via the<br>RS485 communication terminals.<br>ON (1): Communication is carried out via the light-<br>loader adapter.  | with communication : OFF (0)<br>without communication : ON (1)                                |              | _                        |
| <b>A (</b> A1)          | Alarm 1-setpoint                        | PV alarm / SP alarm: -100.0 to 100.0% of PV<br>input range<br>Deviation alarm: -100.0 to 100.0% of PV input  | PV high limit/SP high limit alarm:<br>100.0% of PV input range<br>Deviation alarm: 0.0% of PV |              | _                        |
| <b>A2</b>               | Alarm 2-setpoint                        | range span<br>Output alarm: -5.0 to 105.0%<br>An alarm common to the 1.SP to 4.SP parameters.  | input range span<br>Other PV/SP low limit alarm:<br>0.0% of PV input range                    |              | _                        |
| <b>A3</b>               | Alarm 3-setpoint                        | _  | Output high limit alarm: 100.0%<br>Output low limit alarm: 0.0%                               |              | _                        |
|                         | Auto-tuning                             | OFF (0): No auto-tuning<br>1: Auto-tuning for 1.SP 2: Auto-tuning for 2.SP<br>3: Auto-tuning for 3.SP 4: Auto-tuning for 4.SP<br>AUTO (5): Performs auto-tuning to all groups 1 to 4.  | OFF (0)   |              | _                        |
| SE<br>(SC)              | "Super" function                        | <ul> <li>OFF (0): Disable</li> <li>1: Overshoot suppressing function<br/>Suppresses overshoots generated by abrupt<br/>changes in the target setpoint or by<br/>disturbances.</li> <li>2: Hunting suppressing function (Stable mode)<br/>Suitable to stabilize the state of control when<br/>the load varies greatly, or the target setpoint is<br/>changed.</li> <li>Enables to answer the wider characteristic<br/>changes compared with Response mode.</li> <li>3: Hunting suppressing function (Response mode)<br/>Enables quick follow-up and short converging<br/>time of PV for the changed target setpoint.</li> <li>Note: Use "SUPER" function (SC) 2 or 3 in PID<br/>control or PI control.</li> <li>"SUPER" function 2 or 3 is not available in the<br/>following controls:</li> <li>1) ON/OFF control</li> <li>2) P control (control for proportional band only)</li> <li>3) PD control (control for proportional band and<br/>derivative item only)</li> <li>4) Heating/cooling control<br/>Do not use hunting suppressing function when<br/>control processes with response such as flow or<br/>pressure control.</li> </ul> | OFF (0)   |              | Ref.2.1(5)<br>Ref.2.1(6) |
| <b>59.00</b><br>(SP.NO) |   | <ul> <li>0: Use target setpoint via communication.</li> <li>1: Selects target setpoint 1 (1.SP).</li> <li>2: Selects target setpoint 2 (2.SP).</li> <li>3: Selects target setpoint 3 (3.SP).</li> <li>4: Selects target setpoint 4 (4.SP).</li> </ul>  | 1   |              | Ref.4.1(1)               |
| Pi d                    | PID parameter display<br>number         | MENU (0): Move to FL parameter display<br>1Gr (1) to 4Gr (4): Display of each PID<br>parameter   | MENU (0)  |              |                          |

| Parameter<br>Symbol           | Name of Parameter   | Setting Range and Description  | Initial Value  | User Setting | Target Item<br>in CD-ROM |
|-------------------------------|---|--|--|--------------|--------------------------|
| FL                            | PV input filter   | OFF (0), 1 to 120 second.<br>Used when the PV input fluctuates.  | OFF (0)  |              | D (1 1(1)                |
| <b>65</b><br>(BS)             | PV input bias   | -100.0% to 100.0% of PV input<br>range span<br>Used to correct the PV input range.   | 0.0% of PV input range span  |              | Ref.1.1(1)               |
|                               | Setpoint ramp-up-rate   | OFF (0)<br>0.0% + 1 digit of PV input range span<br>to 100.0% of PV input range span   | OFF (0)  |              | Ref.4.1(4)               |
|                               | Setpoint ramp-down-<br>rate   | Set ramp-up-rate or ramp-down-rate<br>per hour or minute.<br>Sets unit in ramp-rate-time unit (TMU).   | OFF (0)  |              | nei.4. ((4)              |
|                               | Output high limit<br>Heating-side output high limit<br>(in heating/cooling control)<br>Output low limit<br>Cooling-side output high limit<br>(in heating/cooling control) | -5.0 to 105.0%<br>Heating-side limiter in heating/cooling<br>control: 0.0 to 105.0% (OL < OH)<br>-5.0 to 105.0%<br>Cooling-side limiter in heating/cooling control: 0.0 to<br>105.0% (OL < OH) | 100%<br>Heating/cooling control:<br>100.0%<br>0.0%<br>Heating/cooling control:<br>100.0%                       |              | Ref.2.1(3)               |
| (H)                           | ON/OFF control hysteresis<br>Heating-side/cooling-side<br>ON/OFF control hysteresis<br>(in heating/cooling control)   | In ON/OFF control: 0.0 to 100.0% of PV input<br>range span<br>In heating/cooling control: 0.0 to 100.0%  | ON/OFF control: 0.5% of PV<br>input range span<br>Heating/cooling control: 0.5%                                |              | _                        |
| dr<br><sub>(DR)</sub>         | Direct/reverse action<br>switching  | 0: reverse action, 1: direct action<br>Control output<br>100%<br>Reverse<br>action<br>- +<br>- 0%<br>Deviation<br>(PV-SP)  | 0  |              | Ref.2.1(1)               |
| НЬ I<br>(HB1)<br>НЬ2<br>(HB2) | Heater burnout current<br>setpoint 1<br>Heater burnout current<br>setpoint 2  | OFF (0), or 1 to 50 A  | OFF (0)  |              |                          |
|                               | Heater burnout current<br>measurement 1<br>Heater burnout current   | These are not setpoints.   | The current value of the<br>heater burnout detector<br>is shown on the display of<br>the HC1 or HC2 parameter. |              | Ref.3.3(5)               |
| (HC2)                         | measurement 2   | 0.04-400.0% of DV investment and   |  |              |                          |
| (ORB)                         | band  | 0.0 to 100.0% of PV input range span   | 1.0% of PV input range<br>span   |              |                          |
| ORH)                          | ON/OFF rate high limit  | ORL + 1 digit to 105.0%  | 100.0%   |              | Ref.3.3(4)               |
|                               | ON/OFF rate low limit   | -5.0% to ORH - 1 digit   | 0.0%   |              |                          |
|                               | On/off rate   | This is not a setpoint.  | The moving average (for 5 cycle times) of the control output is shown.   |              |                          |
| (1.SP)                        | Target setpoint-1   | 0.0 to 100.0% of PV input range<br>However, between target setpoint limiter<br>lower limit (SPL) and upper limit (SPH).  | 0.0% of PV input range   |              |                          |
| <b>2.5P</b><br>(2.SP)         | Target setpoint-2   |  |  |              | Rof / 1(1)               |
| <b>357</b><br>(3.SP)          | Target setpoint-3   |  |  |              | Ref.4.1(1)               |
| <b>45</b><br>(4.SP)           | Target setpoint-4   |  |  |              |                          |

#### • PID-related Parameters

The following parameters are displayed when "1Gr" is set to PID parameter display number (PID).

In this case, the corresponding target setpoint is 1.SP (target setpoint-1).

To set PID corresponding to target setpoint 2 to 4, set "2Gr", "3Gr", or "4Gr" to PID. The relevant parameters will then be displayed.

| Parameter<br>Symbol | Name of Parameter  | Setting Range and Description   | Initial Value                   | User Setting | Target Item<br>in CD-ROM |
|---------------------|--|---|---------------------------------|--------------|--------------------------|
| (1.P)               | Proportional band/Heating-<br>side proportional band<br>(in heating/cooling control) | 0.1 to 999.9%<br>In heating/cooling control: 0.0 to 999.9%<br>(heating-side ON/OFF control applies when 0.0)  | 5.0%                            |              |                          |
| (1.l)               | Integral time<br>Heating-side integral time<br>(in heating/cooling control)          | OFF (0), 1 to 6000 second.  | 240 second.                     |              |                          |
| (1.D)               | Derivative time<br>Heating-side derivative time<br>(in heating/cooling control)      | OFF (0), 1 to 6000 second.  | 60 second.                      |              |                          |
| (1.MR)              | Manual reset   | -5.0 to 105.0%<br>(enabled when integral time "1.1" is OFF)<br>The manual reset value equals the output value<br>when PV = SP is true.<br>For example, if the manual reset value is 50%,<br>the output value is 50% when PV = SP<br>becomes true. | 50.0%                           |              |                          |
|                     | Cooling-side<br>proportional band  | 0.0 to 999.9%<br>(Cooling-side ON/OFF control applies when<br>0.0)  | 5.0%                            |              | Ref.4.1(1)               |
|                     | Cooling-side integral time   | OFF (0), 1 to 6000 second.  | 240 second.                     |              |                          |
|                     | Cooling-side derivative time   | OFF (0), 1 to 6000 second.  | 60 second.                      |              |                          |
| (1.DB)              | Deadband   | -100.0 to 50.0%<br>In heating/cooling control, a reagion where<br>both of the heating- and cooling-side outputs<br>are presented, or non of them is presented,<br>can be set.   | 3.0%                            |              |                          |
| (1.RP)              | Zone PID reference<br>point-1  | 0.0 to 100.0% of PV input range. Note that 1.RP $\leq$ 2.RP.  | 100% value of<br>PV input range |              |                          |

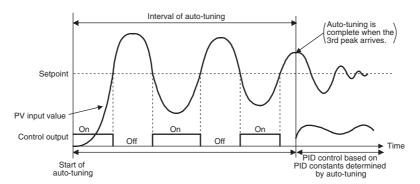
Refer to the table below for recording setpoints when two sets or more of PID parameters are used.

| Parameter | n=2 | n=3  | n=4  |
|-----------|-----|------|------|
| n.P       |     |      |      |
| n.l       |     |      |      |
| n.D       |     |      |      |
| n.MR      |     |      |      |
| n.Pc      |     |      |      |
| n.lc      |     |      |      |
| n.Dc      |     |      |      |
| n.DB      |     |      |      |
| n.RP      |     | None | None |

| (RDV) | Reference deviation | OFF (0), 0.0 to100.0% of PV input range span<br>Used to select PID constants according to a deviation from<br>the setpoint. The 4th group of PID constants is used<br>when the controller fails to keep track of the deviation. | OFF (0) |  | Ref.4.1(1) |
|-------|---------------------|---|---------|--|------------|
|-------|---------------------|---|---------|--|------------|

#### Auto-tuning

Auto-tuning is a function with which the controller automatically measures the process characteristics to automatically set the optimum PID constants. This function does not work when the controller is performing on-off control. The UT350/UT320 employ the "Limit Cycle Method." As shown in the figure below, the controller temporarily changes its control output in a step-waveform manner. Then, it calculates the optimum proportional band (P), integral time (I) and derivative time (D) from the resulting response to set them in their respective parameters.



If the Output High Limit (OH) and Output Low Limit (OL) parameters are already configured, the control output turns on and off only between the output's high and low limits during auto-tuning.

# ● Auto-tuning Using Zone PID (see "■ PID Switching (Zone PID)" later in this chapter)

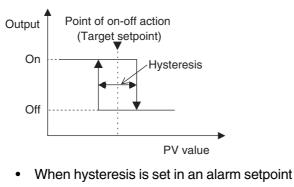
| Setting of<br>AT Parameter | Auto-tuned Setpoint             | Remarks  |
|----------------------------|---------------------------------|--|
| OFF                        | -                               | Auto-tuning is turned off (disabled).                                |
| 1                          | tuning is started               | Determines the values of 1.P, 1.I and 1.D parameters by auto-tuning. |
| 2                          |                                 | Determines the values of 2.P, 2.I and 2.D parameters by auto-tuning. |
| 3                          |                                 | Determines the values of 3.P, 3.I and 3.D parameters by auto-tuning. |
| 4                          |                                 | Determines the values of 4.P, 4.I and 4.D parameters by auto-tuning. |
| AUTO                       | Median value of each zone width | Determines the values of all PID parameters in use by auto-tuning.   |

The AT parameter settings numbered 1 to 4 in the table above are dependent on how many zones have been set. For example, if you have set two zones, you can use AT parameter settings 1 and 2. Likewise, if you have set three zones, you can use AT parameter settings 1, 2 and 3.

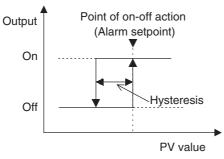
### Hysteresis (for Target Setpoints (On-Off Control) and Alarm Setpoints)

Hysteresis can be set in on-off control setpoints and alarm setpoints as well. With the hysteresis settings, it is possible to prevent relays from chattering.

When hysteresis is set in a target setpoint







#### Target Setpoint Ramp Setting Function

Use this function to prevent the target setpoint from changing suddenly. The ramp setting function works when:

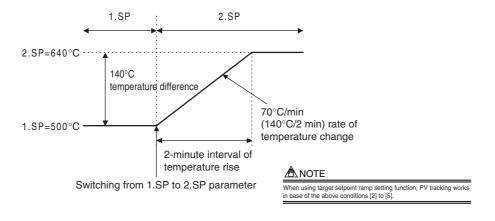
- [1] the target setpoint is changed (example: change in "1.SP" from 100°C to 150°C);
- [2] the target setpoint number is switched (example: switch from "1.SP" to "3.SP");
- [3] the power is turned on or the controller is recovered from power failure;
- [4] a change is made from manual operation to automatic operation; or
- [5] a change is made from the STOP state to the RUN state.

If the target setpoint before switching is smaller than the target setpoint after switching, the controller operates according to the settings of the Setpoint Ramp UP (UPR) and Ramp Time Unit (TMU) parameters. If the target setpoint before switching is greater than the target setpoint after switching, the controller operates according to the settings of the Setpoint Ramp Down (DNR) and Ramp Time Unit (TMU) parameters.

# 

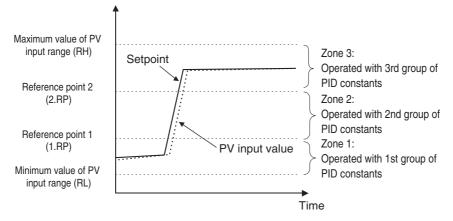
When using target setpoint ramp setting function, PV tracking works in case of the above conditions [2] to [5].

The figure below shows an example when the Target Setpoint Number (SP.NO) parameter is switched. The 1.SP and 2.SP parameters are set to 500°C and 640°C, respectively. Thus, there is a temperature difference of 140°C between the 1.SP and 2.SP parameters. This example shows how the temperature is changed by as much as this temperature difference over a period of two minutes. In this example, the UPR parameter is 70°C and the TMU parameter is 1 minute.



### PID Switching (Zone PID)

Using a zone PID, you can automatically switch between groups of PID constants according to the temperature zone. You can set a maximum of three temperature zones.



#### <Setting Method>

- [1] Set the Zone PID Selection (ZON) parameter to "ON".
- [2] Define a reference point.
   When using two zones, define only reference point 1 (1.RP) between the minimum and maximum values of the PV input range.
   When using three zones, define reference points 1 and 2 (1.RP and 2.RP) in the same way as noted above.

# 

Set the maximum and minimum values, as close as possible to those of the actual range to be controlled, in the Maximum Value of PV Input Range (RH) and Minimum Value of PV Input Range (RL) parameters. Otherwise, the controller may fail to determine the optimum values when auto-tuning is carried out.

## Setup Parameters

### Control Function-related Parameters

| Parameter<br>Symbol  | Name of Parameter   | Setting Range and Description  | Initial Value   | User Setting | Target Item<br>in CD-ROM |
|----------------------|---|--|---|--------------|--------------------------|
| <b>5Р</b> Н<br>(SPH) | Target setpoint limiter<br>upper limit  | 0.0 to 100.0% of PV input range where, SPL < SPH<br>Places a limit on the range within which the target<br>setpoint is changed.  | 100.0% of<br>PV input range                             |              |                          |
| <b>SPL</b>           | Target setpoint limiter<br>lower limit  |  | 0.0% of<br>PV input range                               |              |                          |
|                      | Alarm-1 type  | OFF (0), 1 to 25, 28 to 31<br>1: PV high limit (energized, no stand-by action)<br>2: PV low limit (energized, no stand-by action)  | 1   |              |                          |
|                      | Alarm-2 type  | <ul> <li>3: Deviation high limit (energized, no stand-by action)</li> <li>4: Deviation low limit (energized, no stand-by action)</li> <li>5: Deviation high limit (de-energized, no stand-by action)</li> <li>6: Deviation low limit (de-energized, no stand-by action)</li> </ul> | 2   |              | Ref.3.3(4                |
|                      | Alarm-3 type  | 6: Deviation low limit (de-energized, no stand-by action)<br>These Alarm Type parameters are common to the<br>parameters 1.SP to 4.SP.<br>See "2.5 Changing Alarm Type" for other alarm types.   | 1   |              |                          |
|                      | Alarm-1 hysteresis  | 0.0 to 100.0% of PV input range span<br>Output alarm: 0.0 to 100.0%<br>Hysteresis for PV high limit alarm  | 0.5% of PV<br>input range span<br>Output alarm:<br>0.5% |              |                          |
| HY2)                 | Alarm-2 hysteresis  | Output<br>On<br>On   |   |              | Ref.3.3(2                |
| HY3)                 | Alarm-3 hysteresis  | Off Hysteresis<br>PV value   |   |              |                          |
| <b>ď ' ' ' ' '</b>   | Alarm-1 delay timer   | An alarm is output when the delay timer expires after the alarm setpoint is reached.<br>0.00 to 99.59 (min, sec.) (enabled when alarm-1 type "AL1" is 1 to 20 or 28 to 31)   | 0.00  |              |                          |
| (DY2)                | Alarm-2 delay timer   | 0.00 to 99.59 (min, sec.) (enabled when alarm-2 type<br>"AL2" is 1 to 20 or 28 to 31)  | -   |              |                          |
|                      | Alarm-3 delay timer   | 0.00 to 99.59 (min, sec.) (enabled when alarm-3 type<br>"AL3" is 1 to 20 or 28 to 31)  |   |              |                          |
|                      | Control output cycle time<br>Heating-side control output cycle<br>time (in heating/cooling control) | 1 to 1000 second.  | 30 second.  |              | Ref.3.3(4                |
|                      | Cooling-side control<br>output cycle time   | 1 to 1000 second.  | 30 second.  |              | _                        |
|                      | Preset output/Heating-side<br>preset output<br>(in heating/cooling control)                         | -5.0 to 105.0%<br>In heating/cooling control: Heating side 0.0 to 105.0%<br>In Stop mode, fixed control output can be generated.   | 0.0%  |              | Ref.2.1(8                |
|                      | Cooling-side preset<br>output   | 0.0 to 105.0%<br>In Stop mode, cooling-side fixed control output can be<br>generated.  | 0.0%  |              |                          |

| Parameter<br>Symbol | Name of Parameter                                       | Setting Range and Description  | Initial Value | User Setting | Target Item<br>in CD-ROM |
|---------------------|---|--|---------------|--------------|--------------------------|
|                     | PID control mode  | 0: Standard PID control (with output bump at SP change)<br>1: Fixed Point control (without output bump at SP change)<br>Choose "Fixed Point Control" when controlling pressure or flow rate.   | 0             |              | Ref.2.1(2)               |
|                     | Zone PID selection                                      | OFF: SP selection<br>ON: Zone PID  | OFF           |              | Ref.4.1(2)               |
| (AR)                | Anti-reset windup<br>(Excess integration<br>prevention) | AUTO (0), 50.0 to 200.0%<br>Used when the control output travels up to 100% or down<br>to 0% and stays at this point.<br>The larger SP, the sooner PID computation<br>(integral computation) stops.  | AUTO (0)      |              | Ref.2.1(4)               |
|                     | Ramp-rate time unit setting                             | 0: hour, 1: minute<br>Time unit of setpoint ramp-up (UPR) and setpoint<br>ramp-down (DNR)  | 0             |              | Ref.4.1(4)               |
| (P.SL)              | Protocol selection                                      | 0: PC link communication         1: PC link communication (with sum check)         2: Ladder communication         3: Coordinated master station         4: Coordinated slave station         7: MODBUS (ASCII)         8: MODBUS (RTU)         10: Coordinated slave station (loop-1 mode)         11: Coordinated slave station (loop-2 mode)         (10, 11: When the master station is in dual-loop control, the slave station selects either of the loops to be controlled.) | 0             |              |                          |
| BPS)                | Baud rate   | 0: 600, 1: 1200, 2: 2400, 3: 4800, 4: 9600 (bps)   | 4             |              |                          |
|                     | Parity  | 0: None<br>1: Even<br>2: Odd   | 1             |              | Communicatio             |
| SEP<br>(STP)        | Stop bit  | 1, 2   | 1             |              | function                 |
|                     | Data length   | 7, 8;<br>Fixed at 7, when the P.SL parameter is set to MODBUS (ASCII).<br>Fixed at 8, when the P.SL parameter is set to MODBUS (RTU)<br>or Ladder Communication.   | 8             |              |                          |
|                     | Address   | 1 to 99<br>However, the maximum number of stations connectable<br>is 31.   | 1             |              |                          |
| DL                  | Minimum response<br>time                                | 0 to 10 (× 10 ms)  | 0             |              |                          |

5-12

| Parameter<br>Symbol | Name of Parameter   | Setting Range and Description  | Initial Value                              | User Setting | Target Item<br>in CD-ROM |
|---------------------|---|--|--|--------------|--------------------------|
|                     | PV input type (PV INPUT<br>terminals)<br>(1) - (12) - (13)terminals | OFF (0), 1 to 18, 30, 31, 35 to 37, 40, 41, 50, 51, 55, 56<br>See "Instrument Input Range Codes" in "2. Initial Settings."   | OFF (0)                                    |              | _                        |
|                     | PV input unit   | °C (0): Degree Celsius °F (5): Fahrenheit<br>- (2): No unit<br>(This parameter is not shown for voltage input.)  | °C (0)                                     |              | _                        |
| (RH)                | Max. value of PV input range  | Set the PV input range, however RL < RH<br>-Temperature input<br>Set the range of temperature that is actually controlled.   | Max. value of<br>instrument<br>input range |              | _                        |
| r į                 | Min. value of PV input range  | <ul> <li>Voltage input</li> <li>Set the range of a voltage signal that is applied.</li> <li>The scale across which the voltage signal is actually controlled<br/>should be set using the parameters Maximum Value of PV Input<br/>Scale (SH) and Minimum Value of PV Input Scale (SL).</li> </ul>  | Min. value of<br>instrument<br>input range |              | _                        |
| SdP<br>(SDP)        | PV input decimal point<br>position (displayed<br>at voltage input)  | <ul> <li>0 to 3</li> <li>Set the position of the decimal point of voltage-mode PV input.</li> <li>0: No decimal place</li> <li>1: One decimal place</li> <li>2,3: Two, three decimal places</li> </ul>   | 1  |              | _                        |
| <b>5</b> H<br>(SH)  | Max. value of PV input<br>scale<br>(displayed at voltage input)     | -1999 to 9999, however SL < SH<br>Set the read-out scale of voltage-mode PV input.   | 100.0                                      |              | _                        |
| <b>5</b> 1          | Min. value of PV input<br>scale<br>(displayed at voltage input)     |  | 0.0  |              | _                        |
| r JL<br>(RJC)       | Presence/absence of<br>PV input reference<br>junction compensation  | OFF (0), ON (1)  | ON (1)                                     |              | _                        |
| <b>bSL</b><br>(BSL) | Selection of PV input<br>burnout action                             | OFF (0)<br>1: Up scale<br>2: Down scale  | 1  |              | _                        |
|                     | Control output<br>type  | <ul> <li>0 Time proportional PID relay contact output (terminals()-(2)-(3))</li> <li>1 Time proportional PID voltage pulse output (terminals(6)-(7))</li> <li>2 Current output (terminals(6)-(7))</li> <li>3 ON/OFF control relay contact output (terminals()-(2)-(3))</li> <li>The following 4 to 12 are displayed only for heating/ cooling type controllers.</li> <li>4 Use time relay and the terminals (0) (0)</li> </ul> | 0<br>Heating/cooling<br>type: 4            |              |                          |
|                     |   | <ul> <li>4 Heating-side relay output (terminals ① - ② - ③), cooling-side relay output (terminals ④ - ⑦)</li> <li>5 Heating-side pulse output (terminals ⑥ - ⑦), cooling-side relay output (terminals ④ - ⑦)</li> <li>6 Heating-side current output (terminals ⑥ - ⑦), cooling-side relay output (terminals ④ - ⑦)</li> <li>cooling-side relay output (terminals ④ - ⑦)</li> </ul>  |  |              |                          |
|                     |   | <ul> <li>7 Heating-side relay output (terminals ①- ②- ③), cooling-side pulse output (terminals ④- ⑤)</li> <li>8 Heating-side pulse output (terminals ⑥- ⑦), cooling-side pulse output (terminals ⑭- ⑤)</li> <li>9 Heating-side pulse output (terminals ⑭- ⑥)</li> </ul>  |  |              |                          |
|                     |   | 9       Heating-side current output (terminals (16 - (7)), cooling-side pulse output (terminals (14 - (5))         10       Heating-side relay output (terminals (1 - (2 - (3)), cooling-side current output (terminals (14 - (5))   |  |              |                          |
|                     |   | <ul> <li>Heating-side pulse output (terminals (6 - (7)), cooling-side current output (terminals (4) - (5))</li> <li>Heating-side current output (terminals (6 - (7)), cooling-side current output (terminals (4) - (5))</li> </ul>   |  |              |                          |

#### • Input-/Output-related Parameters

| Parameter<br>Symbol          | Name of Parameter                               |                | Setting Range and Description  | Initial Value             | User Setting | Target Item<br>in CD-ROM |
|------------------------------|---|----------------|--|---------------------------|--------------|--------------------------|
| ret<br>(RET)                 | Retransmission output<br>type                   | In he<br>and o | /, 2: SP, 3: OUT, 4: Loop power supply for sensor (15 V)<br>ating/cooling control, an output value before allocation to heating<br>cooling control (0 to 100%) is transmitted if setpoint "3" is selected<br>50%: Cooling-side output; 50 to 100%: Heating-side output). | 1                         |              |                          |
| <b>г <u>Е</u> Н</b><br>(RTH) | Max. value of<br>retransmission output<br>scale | RET            | RET=1, 2: RTL + 1 digit to 100.0% of PV input range  |                           |              | Ref.2.2(1)               |
| r <b>e</b> L<br>(RTL)        | Min. value of<br>retransmission output<br>scale | RET            | =1, 2: 0.0% of PV input range to RTH - 1 digit   | 0.0% of<br>PV input range |              |                          |
| <u>di 5</u>                  | DI function selection                           | OFF (0)        | Disables the external contact input.<br>DI1: 2.SP (on)/1.SP (off), DI2: AUTO (on)/MAN (off)  | 1                         |              |                          |
| (DIS)                        |   | 2              | DI1: Hides (on)/shows (off) the LOCK setup parameter.<br>DI2: Unused.  |                           |              | Ref.3.1(1)               |
|                              |   | 3              | See the table below.   |                           |              |                          |
|                              |   | 4              | DI1: 2.SP (on)/1.SP (off), DI2: STOP (on)/RUN (off)  |                           |              |                          |

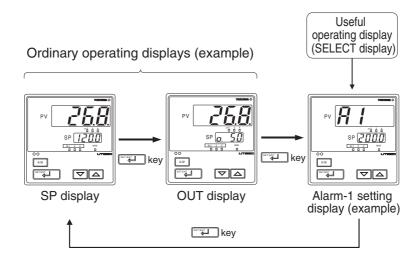
• SP Selection when DIS = 3 is set

|      | DI1 | DI2 |
|------|-----|-----|
| 1.SP | OFF | OFF |
| 2.SP | ON  | OFF |
| 3.SP | OFF | ON  |
| 4.SP | ON  | ON  |

|                       | OFI FOT displays 1 |   |         |            |
|-----------------------|--------------------|---|---------|------------|
| 151                   | SELECT display-1   | OFF (0), 201 to 1015  | OFF (0) |            |
|                       | registration       | Select the desired parameter from among the operating and setup           |         |            |
| (C.S1)                |                    | parameters, then register the number (D register No.) accompanying that   |         |            |
|                       | SELECT display-2   | parameter.  |         |            |
| L.JC                  | registration       | For example, registering "231" for C.S1 allows you to change alarm-1      |         |            |
| (C.S2)                |                    | setpoint in operating display.  |         | Ref.6.1(1) |
|                       | SELECT display-3   | Numbers for registering alarm SP parameter for operating display:         |         |            |
| L.コゴ                  | registration       | Alarm-1 setpoint: 231 Alarm-2 setpoint: 232                               |         |            |
| (C.S3)                |                    | Alarm-3 setpoint: 233   |         |            |
| <b><i><b></b></i></b> | SELECT display-4   | Above numbers are alarm setpoint parameters for target setpoint-1 (1.SP). |         | 1          |
| 154                   | registration       |   |         |            |
| (C.S4)                | 3                  |   |         |            |
| 1 611                 | Key lock           | OFF (0): No key lock  | OFF (0) |            |
| LOLC                  |                    | 1: Change to any parameter prohibited                                     |         |            |
| (LOCK)                |                    | Prohibits any operating parameter or setup parameter from being           |         |            |
| . ,                   |                    | changed.  |         |            |
|                       |                    | The setpoint of the LOCK parameter itself can be changed, however.        |         |            |
|                       |                    | 2: Change to and display of operating parameters prohibited               |         | Ref.7.1(2) |
|                       |                    | Turns off the display for setting operating parameters, thus              |         |            |
|                       |                    | prohibiting any change to the parameter settings.                         |         |            |
|                       |                    | (Hold down the SET/ENT key for more than 3 seconds to show the            |         |            |
|                       |                    | password check display.)  |         |            |
|                       |                    | 3: Disables the A/M key on the instrument's front panel.                  |         |            |
| <b>D</b> 111          | Password setting   | 0: Password not set   | 0       |            |
| 120d                  |                    | 1 to 9999   | -       | Ref.7.1(1) |
| (PWD)                 |                    |   |         |            |

# Useful Operating Displays (SELECT Display)

Registering frequently changed parameters in the SELECT display after ordinary operating displays will allow you to change settings easily. A maximum of four displays can be registered.



### <Setting method>

Set the parameter numbers (D register numbers) you wish to register for setup parameters C.S1 to C.S4.

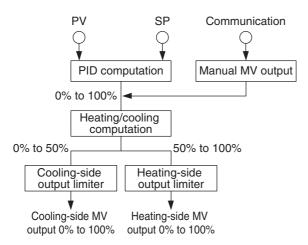
| Alarm parameter for target setpoint-1 | Registration number |
|---------------------------------------|---------------------|
| Alarm-1 setpoint parameter            | 231                 |
| Alarm-2 setpoint parameter            | 232                 |
| Alarm-3 setpoint parameter            | 233                 |

# Heating/Cooling Control (for a Heating/Cooling Controller Only)

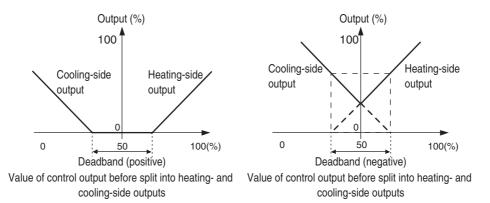
In heating/cooling control, the controller outputs the result of computation after splitting it into heating-purpose and cooling-purpose signals. In addition, the controller can perform PID control or on-off control on the heating and cooling sides separately. When performing on-off control, set the proportional band to "0".

The controller splits the result of computation (0 to 100%) into heating-side and cooling-side signals, as described below.

- 0% to 50% of the computation result is presented as a 0% to 100% cooling-side output.
- 50% to 100% of the computation result is presented as a 0% to 100% heating-side output.



Heating/cooling control provides two methods in which either none of the heating- and cooling-side outputs are presented or both of the heating- and cooling-side outputs are presented, as shown in the following figures.



## **Precautions in Heating/Cooling Control**

- Keep the ratio of the heating-side proportional band (P) to the cooling-side proportional band (Pc) equal to or below 5.
- If neither the heating side nor the cooling side is performing on-off control, setting the integral time (I or Ic) of one side to "0" results in the Integral Time parameters of both sides being set to "OFF", irrespective of the integral time setting of the other side.

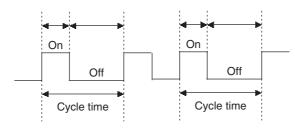
# Cycle Time

A cycle time can only be set if the type of control output is time proportional PID relay output or time proportional voltage pulse output.

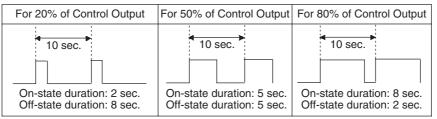
A cycle time refers to one period consisting of on-and off-state time lengths.

The ratio of the on-state time to the off-state time differs according to the value of the control output.

The figure below shows on-to-off time ratios of the control output when the cycle time is set to 10 seconds. Setting a shorter cycle time allows the controller to perform elaborate control at short time intervals. This significantly reduces the on-and off-state times, however it shortens the service life of a relay.



Relay's Behavior when Cycle Time = 10 sec.



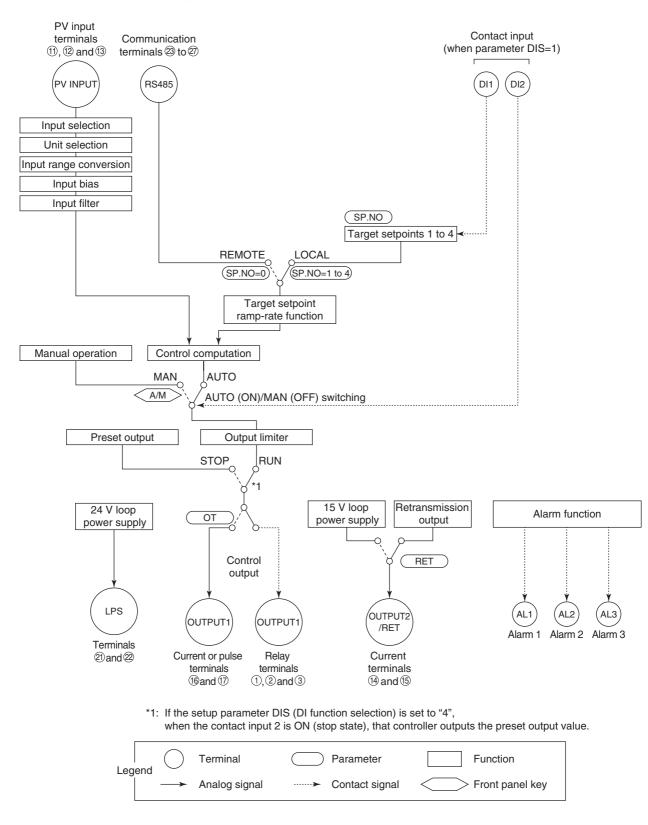
# 6.

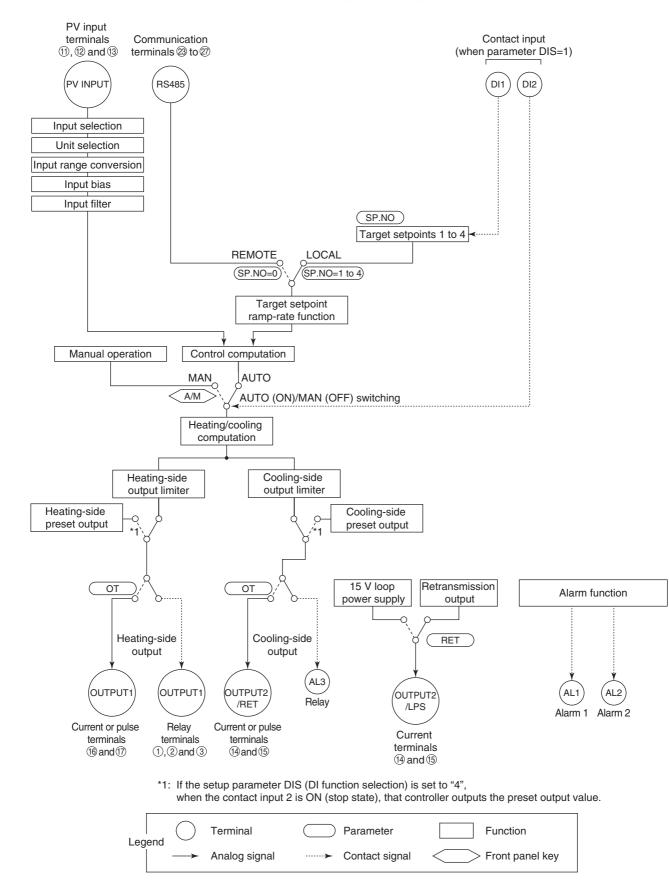
# Function Block Diagram and Descriptions

This chapter contains the function block diagrams for "Standard type," and "Heating/cooling type." For details on these function block diagrams, refer to the descriptions mentioned later.



<Toc>





# ■ Function Block Diagram for Heating/Cooling Type

# Functions and Parameters for "Standard Type" in Initial State (Factory-set default)

Functions and parameters in initial state are given in the tables below. For details on each parameter, refer to "5.2 Lists of Parameters."

# PV Input

PV input (INPUT) is a universal input, which can receive signals from thermocouple, RTD, or DC voltage signals. The controller is capable of biasing, and first-order lag computation (filtering) on input signals.

Each function can be set by the following parameters.

## **Setup Parameters**

| Function               | Parameter            | Menu |
|------------------------|----------------------|------|
| Input selection        | IN                   | I/O  |
| Unit selection         | UNIT                 | I/O  |
| Input range conversion | RH, RL (SDP, SH, SL) | I/O  |

## **Operating Parameters**

| Function        | Parameter | Menu  |
|-----------------|-----------|-------|
| PV input bias   | BS        | OP.PA |
| PV input filter | FL        | OP.PA |

# Remote Input

Remote input can be received via communication. Set "0" in the parameter SP.NO (target setpoint number selection) for remote input. For more information, refer to GREEN Series Communication Functions (IM 05G01B02-01E).

Each function can be set by the following parameters.

## **Operating Parameters**

| Function                         | Parameter | Menu  |
|----------------------------------|-----------|-------|
| Target setpoint number selection | SP.NO     | OP.PA |

# Contact Input

Changing the setpoint of the parameter DIS (DI function selection) allows you to change the function of contact input.

## When DIS=OFF

No function for contact input.

# • When DIS=1 (factory-set default)

Target setpoint 2 (ON)/Target setpoint 1 (OFF) switching function is assigned to DI1 (contact input 1).

Automatic (ON)/Manual (OFF) switching function is assigned to DI2 (contact input 2). Manipulated output can be changed using the  $\bigtriangleup$  and  $\bigtriangledown$  keys in manual mode.

## • When DIS=2

Hide (ON)/Show (OFF) the parameter LOCK (key lock) switching function is assigned to DI1 (contact input 1).

No function is assigned to DI2 (contact input 2).

## • When DIS=3

It is possible to select one out of four setpoints by turning the two contact input signals ON or OFF. This function is assigned to DI1 (contact input 1) and DI2 (contact input 2).

|       | Target setpoint number to be selected (SP.NO) |     |     |    |  |
|-------|---|-----|-----|----|--|
| input | 1   | 2   | 3   | 4  |  |
| DI1   | OFF   | ON  | OFF | ON |  |
| DI2   | OFF   | OFF | ON  | ON |  |

For example, set contact input 1 (DI1) only to "ON" to change target setpoint 1 to 2. Set contact inputs 1 (DI1) and 2 (DI2) to "ON" to select target setpoint 4.

# When DIS=4

Target setpoint 2 (ON)/Target setpoint 1 (OFF) switching function is assigned to DI1 (contact input 1).

Run (OFF)/Stop (ON) switching function is assigned to DI2 (contact input 2). Preset output value is output when the operation is stopped. PV input and alarms remain functioning as normal.

# Target Setpoint and PID

It is possible to use a maximum of four groups of target setpoints and PID parameters. The target setpoint can be selected by key operation or contact input. For selection by contact input, refer to "Contact Input."

## **Operating Parameters**

| Function                         | Parameter | Menu  |
|----------------------------------|-----------|-------|
| Target setpoint number selection | SP.NO     | OP.PA |
| Target setpoints 1 to 4          | n.SP      | OP.PA |
| Proportional band (P)            | n.P       | OP.PA |
| Integral time (I)                | n.l       | OP.PA |
| Derivative time (D)              | n.D       | OP.PA |

Note: Parameters n.SP, n.P, n.I, n.D (n=1 to 4) correspond to the target setpoint number selected in the target setpoint number selection (SP.NO).

The target setpoint ramp rate setting function prevents the target setpoint form changing suddenly. It is possible to set the upward and downward changing rate (i.e., ramp rate) independently in the parameters UPR and DNR. The unit of the ramp rate (hour, or minute) is specified in TMU.

### **Setup Parameters**

| Function                    | Parameter | Menu |
|-----------------------------|-----------|------|
| Ramp-rate time unit setting | TMU       | FUNC |

### **Operating Parameters**

| Function                          | Parameter | Menu  |
|-----------------------------------|-----------|-------|
| Target setpoint ramp-rate setting | UPR, DNR  | OP.PA |

# Control Output

Control output (OUTPUT1) selects the output type among the current output, voltage pulse output, and relay contact output signal.

Preset output value is output when the operation is stopped by key operation or contact input, which takes priority over the manual operation.

Each function can be set by the following parameters.

### **Setup Parameters**

| Function                      | Parameter | Menu |
|-------------------------------|-----------|------|
| Control output type selection | OT        | I/O  |
| Control output cycle time     | СТ        | FUNC |
| Preset output                 | PO        | FUNC |

# **Operating Parameters**

| Function       | Parameter | Menu  |
|----------------|-----------|-------|
| Output limiter | OL, OH    | OP.PA |

# Contact Output

Alarm 1 is output via DO1 (contact output 1).

Alarm 2 is output via DO2 (contact output 2).

Alarm 3 is output via DO3 (contact output 3).

## **Setup Parameters**

| Function     | Parameter | Menu |
|--------------|-----------|------|
| Alarm 1 type | AL1       | FUNC |
| Alarm 2 type | AL2       | FUNC |
| Alarm 3 type | AL3       | FUNC |

## **Operating Parameters**

| Function         | Parameter | Menu  |
|------------------|-----------|-------|
| Alarm 1 setpoint | A1        | OP.PA |
| Alarm 2 setpoint | A2        | OP.PA |
| Alarm 3 setpoint | A3        | OP.PA |

# Retransmission Output

PV, target setpoint, or control output can be output to retransmission output (OUTPUT2/ RET).

Each function can be set by the following parameters.

#### **Setup Parameters**

| Function                    | Parameter | Menu |
|-----------------------------|-----------|------|
| Retransmission output type  | RET       | I/O  |
| Retransmission output scale | RTH, RTL  | I/O  |

# ■ 15 V DC Loop Power Supply

The 15 V DC loop power supply (OUTPUT2/RET) uses the same terminal as retransmission output. The 15 V DC loop power supply can not be used when retransmission output is used. To use the 15 V DC loop power supply, set "4" in retransmission output type selection parameter RET.

Each function can be set by the following parameters.

### **Setup Parameters**

| Function                   | Parameter | Menu |
|----------------------------|-----------|------|
| Retransmission output type | RET       | I/O  |

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